Chapter 5, Section 3

3. (a)

$$A^{T}A = \begin{bmatrix} 6 & 12 \\ 12 & 24 \end{bmatrix}$$
$$A^{T}\mathbf{b} = \begin{bmatrix} 6 \\ 12 \end{bmatrix}$$

The matrix $A^T A$ is not invertible since det $A^T A = 0$. However, there is still a least squares solution. In fact, there are infinite least squares solutions here. We find them by solving the system:

$$A^{T}A\mathbf{x} = A^{T}\mathbf{b}$$

$$\begin{bmatrix} 6 & 12 \\ 12 & 24 \end{bmatrix} \begin{bmatrix} x_{1} \\ x_{2} \end{bmatrix} = \begin{bmatrix} 6 \\ 12 \end{bmatrix}$$

Both equations in the system give us the same equation:

$$x_1 + 2x_2 = 1$$

Let $x_2 = \alpha$. Then $x_1 = 1 - 2x_2 = 1 - 2\alpha$. Therefore, the least squares solutions are:

$$\mathbf{x} = \begin{bmatrix} 1 - 2\alpha \\ \alpha \end{bmatrix}, \quad \alpha \in \mathbb{R}$$

(b)

$$A^{T}A = \begin{bmatrix} 3 & 0 & 6 \\ 0 & 14 & 14 \\ 6 & 14 & 26 \end{bmatrix}$$
$$A^{T}\mathbf{b} = \begin{bmatrix} 6 \\ 14 \\ 26 \end{bmatrix}$$

The matrix $A^T A$ is not invertible since det $A^T A = 0$. However, there is still a least squares solution. In fact, there are infinite least squares solutions here just as in part (a). We find them by solving the system:

$$A^{T}A\mathbf{x} = A^{T}\mathbf{b}$$

$$\begin{bmatrix} 3 & 0 & 6\\ 0 & 14 & 14\\ 6 & 14 & 26 \end{bmatrix} \begin{bmatrix} x_{1}\\ x_{2}\\ x_{3} \end{bmatrix} = \begin{bmatrix} 6\\ 14\\ 26 \end{bmatrix}$$

The row reduced echelon form of the augmented matrix $[A^T A | A^T \mathbf{b}]$ is:

$$\left[\begin{array}{rrrrr} 1 & 0 & 2 & | & 2 \\ 0 & 1 & 1 & | & 1 \\ 0 & 0 & 0 & | & 0 \end{array}\right]$$

The third column does not contain a pivot. Therefore, x_3 is a free variable. Let $x_3 = \alpha$. Then $x_2 = 1 - x_3 = 1 - \alpha$ and $x_1 = 2 - 2x_3 = 2 - 2\alpha$. Therefore, the least squares solutions are:

$\mathbf{x} =$	$\begin{bmatrix} 2-2\alpha \\ 1-\alpha \end{bmatrix}$,	$\alpha \in \mathbb{R}$
	α		

5. (a) A linear function is of the form y = mx + b. Plugging in the data, we get the following system of equations:

$$0 = -1m + b$$

$$1 = 0m + b$$

$$3 = 1m + b$$

$$9 = 2m + b$$

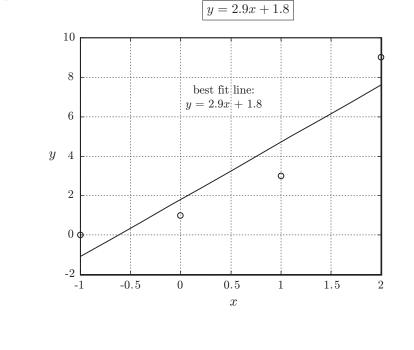
In matrix-vector format, the system is:

$$\begin{bmatrix} -1 & 1 \\ 0 & 1 \\ 1 & 1 \\ 2 & 1 \end{bmatrix} \underbrace{\begin{bmatrix} m \\ b \end{bmatrix}}_{\mathbf{x}} = \underbrace{\begin{bmatrix} 0 \\ 1 \\ 3 \\ 9 \end{bmatrix}}_{\mathbf{b}}$$

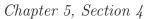
The least squares solution is:

$$\mathbf{x} = (A^T A)^{-1} A^T \mathbf{b} = \begin{bmatrix} 2.9\\1.8 \end{bmatrix}$$

The equation of the best fit line is:



(b)



4. (a)
$$\langle A, B \rangle = (1)(-4) + (2)(1) + (2)(1) + (1)(-3) + (0)(3) + (2)(2) + (3)(1) + (1)(-2) + (1)(-2) = \boxed{0}$$

(b) $||A||_F = \sqrt{1^2 + 2^2 + 2^2 + 1^2 + 0^2 + 2^2 + 3^2 + 1^2 + 1^2} = \boxed{5}$
(c) $||B||_F = \sqrt{(-4)^2 + 1^2 + 1^2 + (-3)^2 + 3^2 + 2^2 + 1^2 + (-2)^2 + (-2)^2} = \boxed{7}$
(d) $||A + B||_F = \sqrt{(-3)^2 + 3^2 + 3^2 + (-2)^2 + 3^2 + 4^2 + 4^2 + (-1)^2 + (-1)^2} = \boxed{\sqrt{74}}$

7. (a)
$$\langle e^x, e^{-x} \rangle = \int_0^1 e^x e^{-x} dx = \int_0^1 dx = 1$$

(b) $\langle x, \sin \pi x \rangle = \int_0^1 x \sin \pi x dx = \left[\frac{\sin \pi x}{\pi^2} - \frac{x \cos \pi x}{\pi} \right]_0^1 = \frac{1}{\pi}$
(c) $\langle x^2, x^3 \rangle = \int_0^1 x^2 x^3 dx = \int_0^1 x^5 dx = \frac{1}{6}$