The shape of the minimal set of the Kuperberg plug

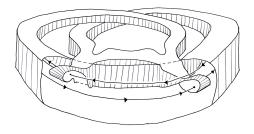
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Joint work with Steven Hurder (University of Illinois at Chicago)

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Theorem (K. Kuperberg, 1994)

Let M be a closed 3-manifold. Then M admits a C^{∞} , or even real analytic, non-vanishing vector field with no periodic orbits.



Theorem

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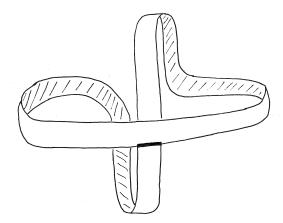
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Definition (Stable shape)

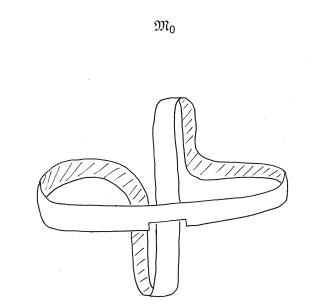
A compact set Σ has stable shape if there exists a shape approximation $\mathfrak{U} = \{U_{\ell} \mid \ell = 1, 2, ...\}$ such that each inclusion $\iota: U_{\ell+1} \hookrightarrow U_{\ell}$ induces a homotopy equivalence, and U_1 has the homotopy type of a finite polyhedron.

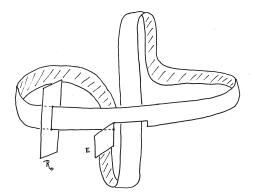
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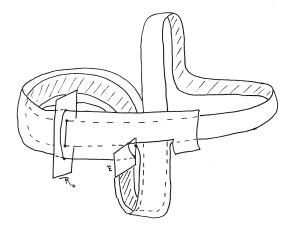


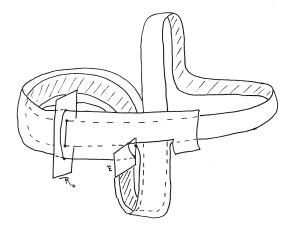




Set $f : E \to \mathbb{R}$ the distance of a point to the special point $\partial R \cap E$.

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Construction of \mathfrak{M}_k from \mathfrak{M}_{k-1} for $k \geq 2$.

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 $\Sigma \subset \mathbb{R}^3$ has unstable shape.

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Proposition (Strategy of proof)

Let U_n be a shape approximation of Σ such that for every $k \ge 2$:

- the rank of $H_1(U_k; \mathbb{Z}) > 2^{k-1}$;
- there exists $\ell > k$ such that the rank of the image $H_1(U_\ell; \mathbb{Z}) \to H_1(U_K; \mathbb{Z})$ is 2.

Assume that for any shape approximation V_n the rank of $H_1(V_n; \mathbb{Z})$ is greater than 2, then Σ has unstable shape.

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Proof.

Assume that Σ has stable shape and let V_n be a good shape approximation. Set $n_0 > 2$ to be the rank of the image $H_1(V_k) \to H_1(V_\ell)$, for every $k \ge \ell$ and ℓ big enough. Take U_n as in the statement.

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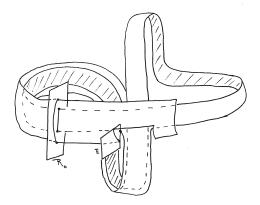
For ℓ big enough, $\exists n_1, k_1, n_2, k_2$ such that $V_{n_2} \subset U_{k_2} \subset V_{n_1} \subset U_{k_1} \subset V_{\ell}$ and

$$H_1(V_{n_2}) \to H_1(U_{k_2}) \to H_1(V_{n_1}) \to H_1(U_{k_1}) \to H_1(V_{\ell}).$$

Shape approximation

Nesting property

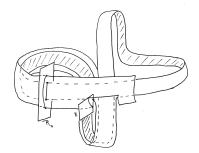
The set $\mathfrak{M}_k \setminus \mathfrak{M}_{k-1}$ admits a one sided closed neighborhood F_k that contains $\mathfrak{M} \setminus \mathfrak{M}_{k-1}$.



Shape approximation

Set

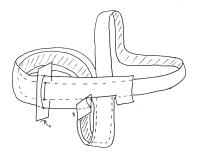
 $\mathfrak{N}_1 = (\mathfrak{M}_0, \delta_0) \cup F_1.$



Shape approximation

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In general

$$\mathfrak{N}_{k}=(\mathfrak{M}_{k-1},\delta_{k-1})\cup F_{k}.$$

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