# Eigenvalues of Non-Regular Linear Quasirandom Hypergraphs 

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#### Abstract

In the paper "Eigenvalues and Linear Quasirandom Hypergraphs", the authors defined a spectral quasirandom property for $k$-uniform hypergraphs which extends the well-known graph property of the separation of the first and second largest eigenvalues of the adjacency matrix of a graph. The authors proved this spectral property is equivalent to several other hypergraph quasirandom properties, but to simplify the presentation only proved the equivalence for so-called $k$-uniform, coregular hypergraphs with loops. This paper extends the results of "Eigenvalues and Linear Quasirandom Hypergraphs" by proving this equivalence for all $k$-uniform hypergraphs, not just the coregular ones.


## 1 Introduction

The study of quasirandom or pseudorandom graphs was initiated by Thomason [18, 19] and then refined by Chung, Graham, and Wilson [7], resulting in a list of equivalent (deterministic) properties of graph sequences which are inspired by $G(n, p)$. Almost immediately after proving their graph theorem, Chung and Graham $[2,3,4,5,6]$ began investigating a $k$-uniform hypergraph generalization. Since then, many authors have studied hypergraph quasirandomness $[1,8,9,12,13,14,15,16,17]$.

One important $k$-uniform hypergraph quasirandom property is Disc, which states that all sufficiently large vertex sets have the same edge density as the entire hypergraph. Kohayakawa, Nagle, Rödl, and Schacht [14] and Conlon, Hàn, Person, and Schacht [8] studied Disc and found several properties equivalent to it, but were not able to find a generalization of a graph property called Eig. In graphs, Eig states that the first and second largest (in

[^0]absolute value) eigenvalues of the adjacency matrix are separated. The authors [16] answered this question by defining a property Eig for $k$-uniform hypergraphs and showed that it is equivalent to Disc, but only proved this for so-called coregular sequences. In this paper, we build up the additional algebra required to prove this equivalence for all $k$-uniform hypergraph sequences, not just the coregular ones. Before stating our result, we need some definitions.

Let $k \geq 2$ be an integer and let $\pi$ be a proper partition of $k$, by which we mean that $\pi$ is an unordered list of at least two positive integers whose sum is $k$. For the partition $\pi$ of $k$ given by $k=k_{1}+\cdots+k_{t}$, we will abuse notation by saying that $\pi=k_{1}+\cdots+k_{t}$. A $k$-uniform hypergraph with loops $H$ consists of a finite set $V(H)$ and a collection $E(H)$ of $k$-element multisets of elements from $V(H)$. Informally, every edge has size exactly $k$ but a vertex is allowed to be repeated inside of an edge. If $F$ and $G$ are $k$-uniform hypergraphs with loops, a labeled copy of $F$ in $H$ is an edge-preserving injection $V(F) \rightarrow V(H)$, i.e. an injection $\alpha: V(F) \rightarrow V(H)$ such that if $E$ is an edge of $F$, then $\{\alpha(x): x \in E\}$ is an edge of $H$. The following is our main theorem.

Theorem 1. Let $0<p<1$ be a fixed constant and let $\mathcal{H}=\left\{H_{n}\right\}_{n \rightarrow \infty}$ be a sequence of $k$-uniform hypergraphs with loops such that $\left|V\left(H_{n}\right)\right|=n$ and $\left|E\left(H_{n}\right)\right| \geq p\binom{n}{k}$. Let $\pi=$ $k_{1}+\cdots+k_{t}$ be a proper partition of $k$ and let $\ell \geq 2$. Assume that $\mathcal{H}$ satisfies the property

- Cycle $e_{4 \ell}[\pi]:$ the number of labeled copies of $C_{\pi, 4 \ell}$ in $H_{n}$ is at most $p^{\left|E\left(C_{\pi, 4 \ell}\right)\right|} n^{\left|V\left(C_{\pi, 4 \ell}\right)\right|}+$ $o\left(n^{\left|V\left(C_{\pi, 4 \ell}\right)\right|}\right)$, where $C_{\pi, 4 \ell}$ is the hypergraph cycle of type $\pi$ and length $4 \ell$ defined in [16, Section 2].

Then $\mathcal{H}$ satisfies the property

- Eig[ $\pi]: \lambda_{1, \pi}\left(H_{n}\right)=p n^{k / 2}+o\left(n^{k / 2}\right)$ and $\lambda_{2, \pi}\left(H_{n}\right)=o\left(n^{k / 2}\right)$, where $\lambda_{1, \pi}\left(H_{n}\right)$ and $\lambda_{2, \pi}\left(H_{n}\right)$ are the first and second largest eigenvalues of $H_{n}$ with respect to $\pi$, defined in Section 2.

When Theorem 1 is combined with [16], we obtain the following theorem.
Theorem 2. Let $0<p<1$ be a fixed constant and let $\mathcal{H}=\left\{H_{n}\right\}_{n \rightarrow \infty}$ be a sequence of $k$-uniform hypergraphs with loops such that $\left|V\left(H_{n}\right)\right|=n$ and $\left|E\left(H_{n}\right)\right| \geq p\binom{n}{k}+o\left(n^{k}\right)$. Let $\pi=k_{1}+\cdots+k_{t}$ be a proper partition of $k$. The following properties are equivalent:

- Eig $[\pi]: \lambda_{1, \pi}\left(H_{n}\right)=p n^{k / 2}+o\left(n^{k / 2}\right)$ and $\lambda_{2, \pi}\left(H_{n}\right)=o\left(n^{k / 2}\right)$, where $\lambda_{1, \pi}\left(H_{n}\right)$ and $\lambda_{2, \pi}\left(H_{n}\right)$ are the first and second largest eigenvalues of $H_{n}$ with respect to $\pi$, defined in Section 2.
- Expand[ $\pi]$ : For all $S_{i} \subseteq\binom{V\left(H_{n}\right)}{k_{i}}$ where $1 \leq i \leq t$,

$$
e\left(S_{1}, \ldots, S_{t}\right)=p \prod_{i=1}^{t}\left|S_{i}\right|+o\left(n^{k}\right)
$$

where $e\left(S_{1}, \ldots, S_{t}\right)$ is the number of tuples $\left(s_{1}, \ldots, s_{t}\right)$ such that $s_{1} \cup \cdots \cup s_{t}$ is a hyperedge and $s_{i} \in S_{i}$.

- Count[ $\pi$-linear]: If $F$ is an $f$-vertex, $m$-edge, $k$-uniform, $\pi$-linear hypergraph, then the number of labeled copies of $F$ in $H_{n}$ is $p^{m} n^{f}+o\left(n^{f}\right)$. The definition of $\pi$-linear appears in [16, Section 1].
- Cycle $e_{4}[\pi]$ : The number of labeled copies of $C_{\pi, 4}$ in $H_{n}$ is at most $p^{\left|E\left(C_{\pi, 4}\right)\right|} n^{\left|V\left(C_{\pi, 4}\right)\right|}+$ $o\left(n^{\left|V\left(C_{\pi, 4}\right)\right|}\right)$, where $C_{\pi, 4}$ is the hypergraph four cycle of type $\pi$ which is defined in [16, Section 2].
- Cycle $e_{4 \ell}[\pi]:$ the number of labeled copies of $C_{\pi, 4 \ell}$ in $H_{n}$ is at most $p^{\mid E\left(C_{\pi, 4 \ell}| |\right.} n^{\left|V\left(C_{\pi, 4 \ell}\right)\right|}+$ $o\left(n^{\left|V\left(C_{\pi}, 4\right)\right|}\right)$, where $C_{\pi, 4 \ell}$ is the hypergraph cycle of type $\pi$ and length $4 \ell$ defined in [16, Section 2].

The remainder of this paper is organized as follows. Section 2 contains the definitions we will require from [16] and also an overview of the proof of Theorem 1. Section 3 contains the algebraic properties required for the proof of Theorem 1, and finally Section 4 contains the proof of Theorem 1.

## 2 Definitions and Overview

First, let us recall the proof of $\mathrm{Cycle}_{4}[1+1] \Rightarrow \operatorname{Eig}[1+1]$ for regular graphs. If $A$ is the adjacency matrix of a graph $G$, then $A^{4}$ counts walks of length 4 in the sense that the $(i, j)$ th entry of $A^{4}$ is the number of walks of length 4 between $i$ and $j$. The trace of $A^{4}$ is then the number of circuits of length 4 in $G$. The trace of a square real symmetric matrix is the sum of its eigenvalues. If $G$ is $d$-regular, then the largest eigenvalue of $A^{4}$ is $d^{4}$ so if the number of circuits of length four in $G$ is $d^{4}+o\left(n^{4}\right)$, then the trace of $A^{4}$ is $d^{4}+o\left(n^{4}\right)$ which implies that all the eigenvalues of $A$ besides $d$ are $o(n)$.

For non-regular graphs having density $p$, Chung, Graham, and Wilson [7] proved that in a graph sequence satisfying $\operatorname{Eig}[1+1]$, the distance between the all-ones vector and the eigenvector corresponding to the largest eigenvalue is $o(1)$ (see the bottom of page 350 in [7]). The reason for this is that if $A$ is the adjacency matrix and $v$ the unit length eigenvector corresponding to the largest eigenvalue, then the second largest eigenvalue of $A$ is the spectral norm of $A-\lambda_{1} v v^{T}$. But as the proof of the (non-regular) Expander Mixing Lemma shows, Expand $[1+1]$ is related to a bound on the spectral norm of $A-p n 1 \hat{1}^{T}$, where $\hat{1}$ is the all-ones vector scaled to unit length (note $n \hat{1} \hat{1}^{T}=J$, the all-ones matrix). Indeed, if $S, T \subseteq V(G)$ and $\chi_{S}$ and $\chi_{T}$ are the indicator vectors for $S$ and $T$ respectively, then $e(S, T)-p|S||T|$ is exactly $\chi_{S}^{T}\left(A-p n \hat{1}^{T}\right) \chi_{T}$. Chung, Graham, and Wilson [7] proved that $\|v-\hat{1}\|=o(1)$ to conclude that $A-\lambda_{1} v v^{T}$ and $A-p n \hat{1} \hat{1}^{T}$ are almost the same matrix so their spectral norms are asymptotically equal, so a bound on $\lambda_{2}(A)$ also bounds $\left\|A-p n \hat{1} \hat{1}^{T}\right\|$. Proposition 3 extends this to hypergraphs, and is our main result. Before stating this proposition, we recall several definitions from [16].

Definition. (Friedman and Wigderson [10, 11]) Let $H$ be a $k$-uniform hypergraph with loops. The adjacency map of $H$ is the symmetric $k$-linear map $\tau_{H}: W^{k} \rightarrow \mathbb{R}$ defined as
follows, where $W$ is the vector space over $\mathbb{R}$ of dimension $|V(H)|$. First, for all $v_{1}, \ldots, v_{k} \in$ $V(H)$, let

$$
\tau_{H}\left(e_{v_{1}}, \ldots, e_{v_{k}}\right)= \begin{cases}1 & \left\{v_{1}, \ldots, v_{k}\right\} \in E(H) \\ 0 & \text { otherwise }\end{cases}
$$

where $e_{v}$ denotes the indicator vector of the vertex $v$, that is the vector which has a one in coordinate $v$ and zero in all other coordinates. We have defined the value of $\tau_{H}$ when the inputs are standard basis vectors of $W$. Extend $\tau_{H}$ to all the domain linearly.

Definition. Let $W$ be a finite dimensional vector space over $\mathbb{R}$, let $\sigma: W^{k} \rightarrow \mathbb{R}$ be any $k$-linear function, and let $\vec{\pi}$ be a proper ordered partition of $k$, so $\vec{\pi}=\left(k_{1}, \ldots, k_{t}\right)$ for some integers $k_{1}, \ldots, k_{t}$ with $t \geq 2$. Now define a $t$-linear function $\sigma_{\vec{\pi}}: W^{\otimes k_{1}} \times \cdots \times W^{\otimes k_{t}} \rightarrow \mathbb{R}$ by first defining $\sigma_{\vec{\pi}}$ when the inputs are basis vectors of $W^{\otimes k_{i}}$ and then extending linearly. For each $i, B_{i}=\left\{b_{i, 1} \otimes \cdots \otimes b_{i, k_{i}}: b_{i, j}\right.$ is a standard basis vector of W$\}$ is a basis of $W^{\otimes k_{i}}$, so for each $i$, pick $b_{i, 1} \otimes \cdots \otimes b_{i, k_{i}} \in B_{i}$ and define

$$
\sigma_{\vec{\pi}}\left(b_{1,1} \otimes \cdots \otimes b_{1, k_{1}}, \ldots, b_{t, 1} \otimes \cdots \otimes b_{t, k_{t}}\right)=\sigma\left(b_{1,1}, \ldots, b_{1, k_{1}}, \ldots, b_{t, 1}, \ldots, b_{t, k_{t}}\right)
$$

Now extend $\sigma_{\vec{\pi}}$ linearly to all of the domain. $\sigma_{\vec{\pi}}$ will be $t$-linear since $\sigma$ is $k$-linear.
Definition. Let $W_{1}, \ldots, W_{k}$ be finite dimensional vector spaces over $\mathbb{R}$, let $\|\cdot\|$ denote the Euclidean 2-norm on $W_{i}$, and let $\phi: W_{1} \times \cdots \times W_{k} \rightarrow \mathbb{R}$ be a $k$-linear map. The spectral norm of $\phi$ is

$$
\|\phi\|=\sup _{\substack{x_{i} \in W_{i} \\\left\|x_{i}\right\|=1}}\left|\phi\left(x_{1}, \ldots, x_{k}\right)\right| .
$$

Definition. Let $H$ be a $k$-uniform hypergraph with loops and let $\tau=\tau_{H}$ be the ( $k$-linear) adjacency map of $H$. Let $\pi$ be any (unordered) partition of $k$ and let $\vec{\pi}$ be any ordering of $\pi$. The largest and second largest eigenvalues of $H$ with respect to $\pi$, denoted $\lambda_{1, \pi}(H)$ and $\lambda_{2, \pi}(H)$, are defined as

$$
\lambda_{1, \pi}(H):=\left\|\tau_{\vec{\pi}}\right\| \quad \text { and } \quad \lambda_{2, \pi}(H):=\left\|\tau_{\vec{\pi}}-\frac{k!|E(H)|}{n^{k}} J_{\vec{\pi}}\right\| .
$$

Definition. Let $V_{1}, \ldots, V_{t}$ be finite dimensional vector spaces over $\mathbb{R}$ and let $\phi, \psi: V_{1} \times$ $\cdots \times V_{t} \rightarrow \mathbb{R}$ be $t$-linear maps. The product of $\phi$ and $\psi$, written $\phi * \psi$, is a $(t-1)$-linear map defined as follows. Let $u_{1}, \ldots, u_{t-1}$ be vectors where $u_{i} \in V_{i}$. Let $\left\{b_{1}, \ldots, b_{\operatorname{dim}\left(V_{t}\right)}\right\}$ be any orthonormal basis of $V_{t}$.

$$
\begin{gathered}
\phi * \psi:\left(V_{1} \otimes V_{1}\right) \times\left(V_{2} \otimes V_{2}\right) \times \cdots \times\left(V_{t-1} \otimes V_{t-1}\right) \rightarrow \mathbb{R} \\
\phi * \psi\left(u_{1} \otimes v_{1}, \ldots, u_{t-1} \otimes v_{t-1}\right):=\sum_{j=1}^{\operatorname{dim}\left(V_{t}\right)} \phi\left(u_{1}, \ldots, u_{t-1}, b_{j}\right) \psi\left(v_{1}, \ldots, v_{t-1}, b_{j}\right)
\end{gathered}
$$

Extend the map $\phi * \psi$ linearly to all of the domain to produce a $(t-1)$-linear map.

Lemma 5 shows that the maps are well defined: the map is the same for any choice of orthonormal basis by the linearity of $\phi$ and $\psi$.

Definition. Let $V_{1}, \ldots, V_{t}$ be finite dimensional vector spaces over $\mathbb{R}$ and let $\phi: V_{1} \times \cdots \times$ $V_{t} \rightarrow \mathbb{R}$ be a $t$-linear map and let $s$ be an integer $0 \leq s \leq t-1$. Define

$$
\phi^{2^{s}}: V_{1}^{\otimes 2^{s}} \times \cdots \times V_{t-s}^{\otimes 2^{s}} \rightarrow \mathbb{R}
$$

where $\phi^{2^{0}}:=\phi$ and $\phi^{2^{s}}:=\phi^{2^{s-1}} * \phi^{2^{s-1}}$.
Note that we only define this for exponents which are powers of two because the product * is only defined when the domains of the maps are the same. An expression like $\phi^{3}=\phi *(\phi * \phi)$ does not make sense because $\phi$ and $\phi * \phi$ have different domains. This defines the power $\phi^{2^{t-1}}$, which is a linear map $V_{1}^{\otimes 2^{t-1}} \rightarrow \mathbb{R}$.

Definition. Let $V_{1}, \ldots, V_{t}$ be finite dimensional vector spaces over $\mathbb{R}$ and let $\phi: V_{1} \times \cdots \times$ $V_{t} \rightarrow \mathbb{R}$ be a $t$-linear map and define $A\left[\phi^{2^{t-1}}\right]$ to be the following square matrix/bilinear map. Let $u_{1}, \ldots, u_{2^{t-2}}, v_{1}, \ldots, v_{2^{t-2}}$ be vectors where $u_{i}, v_{i} \in V_{1}$.

$$
\begin{gathered}
A\left[\phi^{2^{t-1}}\right]: V_{1}^{\otimes 2^{t-2}} \times V_{1}^{\otimes 2^{t-2}} \rightarrow \mathbb{R} \\
A\left[\phi^{2^{t-1}}\right]\left(u_{1} \otimes \cdots \otimes u_{2^{t-2}}, v_{1} \otimes \ldots v_{2^{t-2}}\right):=\phi^{2^{t-1}}\left(u_{1} \otimes v_{1} \otimes u_{2} \otimes v_{2} \otimes \cdots \otimes u_{2^{t-2}} \otimes v_{2^{t-2}}\right) .
\end{gathered}
$$

Extend the map linearly to the entire domain to produce a bilinear map.
Lemma 7 below proves that $A\left[\phi^{2^{t-1}}\right]$ is a square symmetric real valued matrix. The following is the main result of this note.

Proposition 3. Let $\left\{\psi_{r}\right\}_{r \rightarrow \infty}$ be a sequence of symmetric $k$-linear maps, where $\psi_{r}: V_{r}^{k} \rightarrow \mathbb{R}$, $V_{r}$ is a vector space over $\mathbb{R}$ of finite dimension, and $\operatorname{dim}\left(V_{r}\right) \rightarrow \infty$ as $r \rightarrow \infty$. Let $\hat{1}$ denote the all-ones vector in $V_{r}$ scaled to unit length and let $J: V_{r}^{k} \rightarrow \mathbb{R}$ be the $k$-linear all-ones map. Let $\pi$ be a proper (unordered) partition of $k$, and assume that for every ordering $\vec{\pi}$ of $\pi$,

$$
\begin{aligned}
& \lambda_{1}\left(A\left[\psi_{\vec{\pi}}^{2 t-1}\right]\right)=(1+o(1)) \psi(\hat{1}, \ldots, \hat{1})^{2^{t-1}} \\
& \lambda_{2}\left(A\left[\psi_{\vec{\pi}}^{2 t-1}\right]\right)=o\left(\lambda_{1}\left(A\left[\psi_{\vec{\pi}}^{2^{t-1}}\right]\right)\right) .
\end{aligned}
$$

Then for every ordering $\vec{\pi}$ of $\pi$,

$$
\left\|\psi_{\vec{\pi}}-q J_{\vec{\pi}}\right\|=o(\psi(\hat{1}, \ldots, \hat{1})),
$$

where $q=\operatorname{dim}\left(V_{r}\right)^{-k / 2} \psi(\hat{1}, \ldots, \hat{1})$.
For graphs, $A\left[\tau^{2}\right]$ is the adjacency matrix squared so Proposition 3 states that the spectral norm of $A-\frac{2|E(G)|}{n^{2}} J$ is little-o of the square root of the largest eigenvalue of $A^{2}$, exactly what is proved by Chung, Graham, and Wilson (see the bottom of page 350 in [7]). The proof appears in the next section.

## 3 Algebraic properties of multilinear maps

In this section we prove several algebraic facts about multilinear maps, including Proposition 3. Throughout this section, $V$ and $V_{i}$ are finite dimensional vector spaces over $\mathbb{R}$. Also in this section we make no distinction between bilinear maps and matrices, using whichever formulation is convenient. We will use a symbol - to denote the input to a linear map; for example, if $\phi: V_{1} \times V_{2} \times V_{3} \rightarrow \mathbb{R}$ is a trilinear map and $x_{1} \in V_{1}$ and $x_{2} \in V_{2}$, then by the expression $\phi\left(x_{1}, x_{2}, \cdot\right)$ we mean the linear map from $V_{3}$ to $\mathbb{R}$ which takes a vector $x_{3} \in V_{3}$ to $\phi\left(x_{1}, x_{2}, x_{3}\right)$. Lastly, we use several basic facts about tensors, all of which follow from the fact that for finite dimensional spaces, the tensor product of $V$ and $W$ is the vector space over $\mathbb{R}$ of dimension $\operatorname{dim}(V) \operatorname{dim}(W)$. For example, if $x$ and $y$ are unit length, then $x \otimes y$ is also unit length.

Lemma 4. Let $\phi: V \rightarrow \mathbb{R}$ be a linear map. There exists a vector $v$ such that $\phi=\langle v, \cdot\rangle$.
Proof. $v$ is the vector dual to $\phi$ in the dual of the vector space $V$. Alternatively, let the $i$ th coordinate of $v$ be $\phi\left(e_{i}\right)$, since then for any $x$,

$$
\phi(x)=\phi\left(\sum\left\langle x, e_{i}\right\rangle e_{i}\right)=\sum\left\langle x, e_{i}\right\rangle \phi\left(e_{i}\right)=\sum\left\langle x, e_{i}\right\rangle\left\langle v, e_{i}\right\rangle=\langle x, v\rangle .
$$

Lemma 5. Let $\phi, \psi: V_{1} \times \cdots \times V_{t} \rightarrow \mathbb{R}$ be $t$-linear maps. The maps $\phi * \psi$ and $A\left[\phi^{2^{t-1}}\right]$ are well defined. Also, $\phi * \psi$ is basis independent in the sense that the definition of $\phi * \psi$ is independent of the choice of orthonormal basis $b_{1}, \ldots, b_{t}$ of $V_{t}$.
Proof. First, extending the definitions of $\phi * \psi$ and $A\left[\phi^{2^{t-1}}\right]$ linearly to the entire domain (non-simple tensors) is well defined, since $\phi$ and $\psi$ are linear. That is, write each $u_{i}$ and $v_{i}$ in terms of some orthonormal basis and expand each tensor in $V_{i} \otimes V_{i}$ also in terms of this basis. The linearity of $\phi$ and $\psi$ then shows that the definitions of $\phi * \psi$ and $A\left[\phi^{2^{t-1}}\right]$ are well defined and linear. To see basis independence of $\phi * \psi$, by Lemma 4 the linear map $\phi\left(u_{1}, \ldots, u_{t-1}, \cdot\right): V_{t} \rightarrow \mathbb{R}$ equals $\left\langle u^{\prime}, \cdot\right\rangle$ for some vector $u^{\prime}$. Similarly, $\psi\left(v_{1}, \ldots, v_{t}, \cdot\right)$ equals $\left\langle v^{\prime}, \cdot\right\rangle$ for some vector $v^{\prime}$. Then

$$
(\phi * \psi)\left(u_{1} \otimes v_{1}, \ldots, u_{t-1} \otimes v_{t-1}\right)=\sum_{i=1}^{\operatorname{dim}\left(V_{t}\right)}\left\langle u^{\prime}, b_{i}\right\rangle\left\langle v^{\prime}, b_{i}\right\rangle=\left\langle u^{\prime}, v^{\prime}\right\rangle .
$$

The last equality is valid for any orthonormal basis, since the dot product of $u^{\prime}$ and $v^{\prime}$ sums the product of the $i$ th coordinate of $u^{\prime}$ in the basis $\left\{b_{1}, \ldots, b_{\operatorname{dim}\left(V_{t}\right)}\right\}$ with the $i$ th coordinate of $v^{\prime}$ in the basis $\left\{b_{1}, \ldots, b_{\operatorname{dim}\left(V_{t}\right)}\right\}$.
Definition. For $s \geq 0$ and $V$ a finite dimensional vector space over $\mathbb{R}$, define the vector space isomorphism $\Gamma_{V, s}: V^{\otimes 2^{s}} \rightarrow V^{\otimes 2^{s}}$ as follows. If $s=0$, define $\Gamma_{V, 0}$ to be the identity map. If $s \geq 1$, let $\left\{b_{1}, \ldots, b_{\operatorname{dim}(V)}\right\}$ be any orthonormal basis of $V$ and define for all $\left(i_{1}, \ldots, i_{2^{s-1}}, j_{1}, \ldots, j_{2^{s-1}}\right) \in[\operatorname{dim}(V)]^{s}$,

$$
\begin{equation*}
\Gamma_{V, s}\left(b_{i_{1}} \otimes b_{j_{1}} \otimes \cdots \otimes b_{i_{2 s-1}} \otimes b_{j_{2^{s-1}}}\right)=b_{j_{1}} \otimes b_{i_{1}} \otimes \cdots \otimes b_{j_{2 s-1}} \otimes b_{i_{2^{s-1}}} \tag{1}
\end{equation*}
$$

Extend $\Gamma_{V, s}$ linearly to all of $V^{\otimes 2^{s}}$.

Remarks. $\Gamma_{V, s}$ is a vector space isomorphism since it restricts to a bijection of an orthonormal basis to itself. Also, it is easy to see that $\Gamma_{V, s}$ is well defined and independent of the choice of orthonormal basis, since each $b_{i}$ can be written as a linear combination of an orthonormal basis $\left\{b_{1}^{\prime}, \ldots, b_{\operatorname{dim}(V)}^{\prime}\right\}$ and (1) can be expanded using linearity. For notational convenience, we will usually drop the subscript $V$ and write $\Gamma_{s}$ for $\Gamma_{V, s}$.

Lemma 6. Let $\phi: V_{1} \times \cdots \times V_{t} \rightarrow \mathbb{R}$ be a t-linear map, let $0 \leq s \leq t-1$, and let $x_{1} \in V_{1}^{\otimes 2^{s}}, \ldots, x_{t-s} \in V_{t-s}^{\otimes 2^{s}}$. Then

$$
\phi^{2^{s}}\left(x_{1}, \ldots, x_{t-s}\right)=\phi^{2^{s}}\left(\Gamma_{s}\left(x_{1}\right), \ldots, \Gamma_{s}\left(x_{t-s}\right)\right) .
$$

Proof. By induction on $s$. The base case is $s=0$ where $\Gamma_{0}$ is the identity map. Expand the definition of $\phi^{2^{s+1}}$ and use induction to obtain

$$
\begin{array}{r}
\phi^{2^{s+1}}\left(x_{1} \otimes y_{1}, \ldots, x_{t-s-1} \otimes y_{t-s-1}\right)=\sum_{j=1}^{\operatorname{dim}\left(V_{t-s}^{\otimes 2^{s}}\right)} \phi^{2^{s}}\left(x_{1}, \ldots, x_{t-s-1}, b_{j}\right) \phi^{2^{s}}\left(y_{1}, \ldots, y_{t-s-1}, b_{j}\right) \\
=\sum_{j=1}^{\operatorname{dim}\left(V_{t-s}^{\otimes 2^{s}}\right)} \phi^{2^{s}}\left(\Gamma_{s}\left(x_{1}\right), \ldots, \Gamma_{s}\left(x_{t-s-1}\right), \Gamma_{s}\left(b_{j}\right)\right) \phi^{2^{s}}\left(\Gamma_{s}\left(y_{1}\right), \ldots, \Gamma_{s}\left(y_{t-s-1}\right), \Gamma_{s}\left(b_{j}\right)\right) .
\end{array}
$$

But since $\Gamma_{s}$ is a vector space isomorphism, $\left\{\Gamma_{s}\left(b_{1}\right), \ldots, \Gamma_{s}\left(b_{\operatorname{dim}\left(V_{t-s}^{\otimes 2^{s}}\right)}\right)\right\}$ is an orthonormal basis of $V_{t-s}^{\otimes 2^{s}}$. Thus Lemma 5 shows that

$$
\begin{gathered}
\sum_{j=1}^{\operatorname{dim}\left(V_{t-s}^{\otimes 2^{s}}\right)} \phi^{2^{s}}\left(\Gamma_{s}\left(x_{1}\right), \ldots, \Gamma_{s}\left(x_{t-s-1}\right), \Gamma_{s}\left(b_{j}\right)\right) \phi^{2^{s}}\left(\Gamma_{s}\left(y_{1}\right), \ldots, \Gamma_{s}\left(y_{t-s-1}\right), \Gamma_{s}\left(b_{j}\right)\right) \\
\quad=\phi^{2^{s+1}}\left(\Gamma_{s}\left(x_{1}\right) \otimes \Gamma_{s}\left(y_{1}\right), \ldots, \Gamma_{s}\left(x_{t-s-1}\right) \otimes \Gamma_{s}\left(y_{t-s-1}\right)\right)
\end{gathered}
$$

Finally, $\Gamma_{s}\left(x_{i}\right) \otimes \Gamma_{s}\left(y_{i}\right)=\Gamma_{s+1}\left(x_{i} \otimes y_{i}\right)$ (write $x_{i}$ and $y_{i}$ as linear combinations, expand $\Gamma_{s+1}\left(x_{i} \otimes y_{i}\right)$ using linearity, and apply (1)). Thus $\phi^{2^{s+1}}\left(x_{1} \otimes y_{1}, \ldots, x_{t-s-1} \otimes y_{t-s-1}\right)=$ $\phi^{2^{s+1}}\left(\Gamma_{s+1}\left(x_{1} \otimes y_{1}\right), \ldots, \Gamma_{s+1}\left(x_{t-s-1} \otimes y_{t-s-1}\right)\right)$, completing the proof.

Lemma 7. Let $V_{1}, \ldots, V_{t}$ be finite dimensional vector spaces over $\mathbb{R}$. If $\phi: V_{1} \times \cdots \times V_{t} \rightarrow \mathbb{R}$ is a $t$-linear map, then $A\left[\phi^{2^{t-1}}\right]$ is a square symmetric real valued matrix.

Proof. Let $\phi: V_{1} \times \cdots \times V_{t} \rightarrow \mathbb{R}$ be a $t$-linear map. $A\left[\phi^{2^{t-1}}\right]$ is a bilinear map from $V_{1}^{\otimes 2^{t-2}} \times V_{1}^{\otimes 2^{t-2}} \rightarrow \mathbb{R}$ and so is a square matrix of dimension $\operatorname{dim}\left(V_{1}\right)^{2^{t-2}}$. Lemma 6 shows that $A\left[\phi^{2^{t-1}}\right]$ is a symmetric matrix, since

$$
\begin{aligned}
A\left[\phi^{2^{t-1}}\right]\left(x_{1} \otimes \cdots \otimes x_{2^{t-2}}, y_{1} \otimes \cdots \otimes y_{2^{t-2}}\right) & =\phi^{2^{t-1}}\left(x_{1} \otimes y_{1} \otimes \cdots \otimes x_{2^{t-2}} \otimes y_{2^{t-2}}\right) \\
& =\phi^{2^{t-1}}\left(\Gamma\left(x_{1} \otimes y_{1} \otimes \cdots \otimes x_{2^{t-2}} \otimes y_{2^{t-2}}\right)\right) \\
& =\phi^{2^{t-1}}\left(y_{1} \otimes x_{1} \otimes \cdots \otimes y_{2^{t-2}} \otimes x_{2^{t-2}}\right) \\
& =A\left[\phi^{2^{t-1}}\right]\left(y_{1} \otimes \cdots \otimes y_{2^{t-2}}, x_{1} \otimes \cdots \otimes x_{2^{t-2}}\right)
\end{aligned}
$$

The above equation is valid for all $x_{i}, y_{i} \in V_{1}$, in particular for all basis elements of $V_{1}$ which implies that $A\left[\phi^{2^{t-1}}\right](w, z)=A\left[\phi^{2^{t-1}}\right](z, w)$ for all basis vectors $w, z$ of $V_{1}^{\otimes 2^{t-2}}$. Thus $A\left[\phi^{2^{t-1}}\right]$ is a square symmetric real-valued matrix.

Lemma 8. Let $\phi: V_{1} \times \cdots \times V_{t} \rightarrow \mathbb{R}$ be a $t$-linear map and let $x_{1} \in V_{1}, \ldots, x_{t} \in V_{t}$ be unit length vectors. Then

$$
\left|\phi\left(x_{1}, \ldots, x_{t}\right)\right|^{2} \leq\left|\phi^{2}\left(x_{1} \otimes x_{1}, \ldots, x_{t-1} \otimes x_{t-1}\right)\right| .
$$

Proof. Consider the linear map $\phi\left(x_{1}, \ldots, x_{t-1}, \cdot\right)$ which is a linear map from $V_{t}$ to $\mathbb{R}$. By Lemma 4, there exists a vector $w \in V_{t}$ such that $\phi\left(x_{1}, \ldots, x_{t-1}, \cdot\right)=\langle w, \cdot\rangle$. Now expand out the definition of $\phi^{2}$ :

$$
\phi^{2}\left(x_{1} \otimes x_{1}, \ldots, x_{t-1} \otimes x_{t-1}\right)=\sum_{j}\left|\phi\left(x_{1}, \ldots, x_{t-1}, b_{j}\right)\right|^{2}=\sum_{j}\left|\left\langle w, b_{j}\right\rangle\right|^{2}=\langle w, w\rangle
$$

where the last equality is because $\left\{b_{j}\right\}$ is an orthonormal basis of $V_{t}$. Since $\|w\|=\sqrt{\langle w, w\rangle}$,

$$
\left|\phi^{2}\left(x_{1} \otimes x_{1}, \ldots, x_{t-1} \otimes x_{t-1}\right)\right|=|\langle w, w\rangle|=\left|\left\langle w, \frac{w}{\|w\|}\right\rangle\right|^{2}
$$

But since $x_{t}$ is unit length and $\langle w, \cdot\rangle$ is maximized over the unit ball at vectors parallel to $w$ (so maximized at $w /\|w\|$ ), $\left|\left\langle w, \frac{w}{\|w\|}\right\rangle\right| \geq\left|\left\langle w, x_{t}\right\rangle\right|$. Thus

$$
\left|\phi^{2}\left(x_{1} \otimes x_{1}, \ldots, x_{t-1} \otimes x_{t-1}\right)\right|=\left|\left\langle w, \frac{w}{\|w\|}\right\rangle\right|^{2} \geq\left|\left\langle w, x_{t}\right\rangle\right|^{2}=\left|\phi\left(x_{1}, \ldots, x_{t}\right)\right|^{2} .
$$

The last equality used the definition of $w$, that $\phi\left(x_{1}, \ldots, x_{t-1}, \cdot\right)=\langle w, \cdot\rangle$.
Lemma 9. Let $\phi: V_{1} \times \cdots \times V_{t} \rightarrow \mathbb{R}$ be a $t$-linear map and let $x_{1} \in V_{1}, \ldots, x_{t} \in V_{t}$ be unit length vectors. Then for $0 \leq s \leq t-1$,

$$
\left|\phi\left(x_{1}, \ldots, x_{t}\right)\right|^{2^{s}} \leq|\phi^{2^{s}}(\underbrace{x_{1} \otimes \cdots \otimes x_{1}}_{2^{s}}, \cdots, \underbrace{x_{t-s} \otimes \cdots \otimes x_{t-s}}_{2^{s}})|
$$

which implies that

$$
\left|\phi\left(x_{1}, \ldots, x_{t}\right)\right|^{2^{t-1}} \leq|A\left[\phi^{2^{t-1}}\right](\underbrace{x_{1} \otimes \cdots \otimes x_{1}}_{2^{t-2}}, \underbrace{x_{1} \otimes \cdots \otimes x_{1}}_{2^{t-2}})| .
$$

Proof. By induction on $s$. The base case is $s=0$ where both sides are equal and the induction step follows from Lemma 8. By definition of $A\left[\phi^{2^{t-1}}\right]$,

$$
|A\left[\phi^{2^{t-1}}\right](\underbrace{x_{1} \otimes \cdots \otimes x_{1}}_{2^{t-2}}, \underbrace{x_{1} \otimes \cdots \otimes x_{1}}_{2^{t-2}})|=|\phi^{2^{t-1}}(\underbrace{x_{1} \otimes \cdots \otimes x_{1}}_{2^{t-1}})|,
$$

completing the proof.

Lemma 10. Let $V_{1}, \ldots, V_{t}$ be vector spaces over $\mathbb{R}$ and let $\phi: V_{1} \times \cdots \times V_{t} \rightarrow \mathbb{R}$ be a $t$-linear map. Then $\|\phi\|^{2^{t-1}} \leq \lambda_{1}\left(A\left[\phi^{2^{t-1}}\right]\right)$.

Proof. Pick $x_{1}, \ldots, x_{t}$ unit length vectors to maximize $\phi$, so $\phi\left(x_{1}, \ldots, x_{t}\right)=\|\phi\|$. Then Lemma 9 shows that

$$
\|\phi\|^{2^{t-1}}=\left|\phi\left(x_{1}, \ldots, x_{t}\right)\right|^{2^{t-1}} \leq|A\left[\phi^{2^{t-1}}\right](\underbrace{x_{1} \otimes \cdots \otimes x_{1}}_{2^{t-2}}, \underbrace{x_{1} \otimes \cdots \otimes x_{1}}_{2^{t-2}})|
$$

Since $x_{1} \otimes \cdots \otimes x_{1}$ is unit length, the above expression is upper bounded by the spectral norm of $A\left[\phi^{2^{t-1}}\right]$.

Lemma 11. Let $\left\{M_{r}\right\}_{r \rightarrow \infty}$ be a sequence of square symmetric real-valued matrices with dimension going to infinity where $\lambda_{2}\left(M_{r}\right)=o\left(\lambda_{1}\left(M_{r}\right)\right)$. Let $u_{r}$ be a unit length eigenvector corresponding to the largest eigenvalue in absolute value of $M_{r}$. If $\left\{x_{r}\right\}$ is a sequence of unit length vectors such that $\left|x_{r}^{T} M_{r} x_{r}\right|=(1+o(1)) \lambda_{1}\left(M_{r}\right)$, then

$$
\left\|u_{r}-x_{r}\right\|=o(1) .
$$

Consequently, for any unit length sequence $\left\{y_{r}\right\}$ where each $y_{r}$ is perpendicular to $x_{r}$,

$$
\left|y_{r}^{T} M_{r} y_{r}\right|=o\left(\lambda_{1}\left(M_{r}\right)\right) .
$$

Proof. Throughout this proof, the subscript $r$ is dropped; all terms $o(\cdot)$ should be interpreted as $r \rightarrow \infty$. This exact statement was proved by Chung, Graham, and Wilson [7], although they don't clearly state it as such. We give a proof here for completeness using slightly different language but the same proof idea: if $x$ projected onto $u^{\perp}$ is too big then the second largest eigenvalue is too big. Write $x=\alpha v+\beta u$ where $v$ is a unit length vector perpendicular to $u$ and $\alpha, \beta \in \mathbb{C}$ and $\alpha^{2}+\beta^{2}=1$ (since $u$ is an eigenvector it might have complex entries). Let $\phi(x, y)=x^{T} M y$ be the bilinear map corresponding to $M$. Since $u^{T} M v=\lambda_{1} u^{T} v=\lambda_{1}\langle u, v\rangle=0$, we have $\phi(u, v)=0$. This implies that

$$
\begin{aligned}
\phi(x, x) & =\phi(\alpha v+\beta u, \alpha v+\beta u)=\alpha^{2} \phi(v, v)+\beta^{2} \phi(u, u)+2 \alpha \beta \phi(u, v) \\
& =\alpha^{2} \phi(v, v)+\beta^{2} \phi(u, u) .
\end{aligned}
$$

The second largest eigenvalue of $M$ is the largest eigenvalue of $M-\lambda_{1}(M) u u^{T}$ which is the spectral norm of $M-\lambda_{1}(M) u u^{T}$. Thus

$$
\begin{equation*}
|\phi(v, v)|=\left|v^{T} M v\right|=\left|v^{T}\left(M-\lambda_{1}(M) u u^{T}\right) v\right| \leq \lambda_{2}(M) . \tag{2}
\end{equation*}
$$

Using that $\phi(u, u)=\lambda_{1}(M)$ and the triangle inequality, we obtain

$$
\begin{equation*}
|\phi(x, x)| \leq \alpha^{2} \lambda_{2}(M)+\beta^{2} \lambda_{1}(M) . \tag{3}
\end{equation*}
$$

Since $\alpha^{2}+\beta^{2}=1,|\alpha|$ and $|\beta|$ are between zero and one. Combining this with (3) and $|\phi(x, x)|=(1+o(1)) \lambda_{1}(M)$ and $\lambda_{2}(M)=o\left(\lambda_{1}(M)\right)$, we must have $|\beta|=1+o(1)$ which in turn implies that $|\alpha|=o(1)$. Consequently,

$$
\|u-x\|^{2}=\langle u-x, u-x\rangle=\langle u, u\rangle+\langle x, x\rangle-2\langle u, x\rangle=2-2 \beta=o(1) .
$$

Now consider some $y$ perpendicular to $x$ and similarly to the above, write $y=\gamma w+\delta u$ for some unit length vector $w$ perpendicular to $u$ and $\gamma, \delta \in \mathbb{C}$ with $\gamma^{2}+\delta^{2}=1$. Then

$$
\phi(y, y)=\phi(\gamma w+\delta u, \gamma w+\delta u)=\gamma^{2} \phi(w, w)+\delta^{2} \phi(u, u)
$$

and as in (2), we have $|\phi(w, w)| \leq \lambda_{2}(M)$. Thus

$$
|\phi(y, y)| \leq \gamma^{2} \lambda_{2}(M)+\delta^{2} \lambda_{1}(M) .
$$

We want to conclude that the above expression is $o\left(\lambda_{1}(M)\right)$. Since $\lambda_{2}(M)=o\left(\lambda_{1}(M)\right)$, we must prove that $|\delta|=o(1)$ to complete the proof.

$$
\delta=\langle y, u\rangle=\left\langle y, \frac{x-\alpha v}{\beta}\right\rangle=\frac{1}{\beta}(\langle y, x\rangle-\alpha\langle y, v\rangle)=\frac{-\alpha\langle y, v\rangle}{\beta} .
$$

But $|\alpha|=o(1),|\beta|=1+o(1)$, and $\|y\|=\|v\|=1$ so $|\delta|=o(1)$ as required.
Lemma 12. Let $J: V_{1} \times \cdots \times V_{t} \rightarrow \mathbb{R}$ be the all-ones map and let $\overrightarrow{1}_{i}$ be the all-ones vector in $V_{i}$. Then for all $x_{1}, \ldots, x_{t}$ with $x_{i} \in V_{i}$,

$$
\begin{equation*}
J\left(x_{1}, \ldots, x_{t}\right)=\left\langle\overrightarrow{1}_{1}, x_{1}\right\rangle \cdots\left\langle\overrightarrow{1}_{t}, x_{t}\right\rangle . \tag{4}
\end{equation*}
$$

Proof. If $x_{1}, \ldots, x_{t}$ are standard basis vectors, then the left and right hand side of (4) are the same. By linearity, (4) is then the same for all $x_{1}, \ldots, x_{t}$.

Proof of Proposition 3. Again throughout this proof, the subscript $r$ is dropped; all terms $o(\cdot)$ should be interpreted as $r \rightarrow \infty$. Let $\hat{1}$ denote the all-ones vector scaled to unit length in the appropriate vector space. Pick an ordering $\vec{\pi}=\left(k_{1}, \ldots, k_{t}\right)$ of $\pi$. The definition of spectral norm is independent of the choice of the ordering for the entries of $\vec{\pi}$, so $\left\|\psi_{\vec{\pi}}-q J_{\vec{\pi}}\right\|$ is the same for all orderings. Let $w_{1}, \ldots, w_{t}$ be unit length vectors where $\left(\psi_{\vec{\pi}}-q J_{\vec{\pi}}\right)\left(w_{1}, \ldots, w_{t}\right)=\left\|\psi_{\vec{\pi}}-q J_{\vec{\pi}}\right\|$ and write $w_{i}=\alpha_{i} y_{i}+\beta_{i} \hat{1}$ where $y_{i}$ is a unit length vector perpendicular to the all-ones vector and $\alpha_{i}, \beta_{i} \in \mathbb{R}$ with $\alpha_{i}^{2}+\beta_{i}^{2}=1$. Then

$$
\begin{align*}
\left\|\psi_{\vec{\pi}}-q J_{\vec{\pi}}\right\| & =\left(\psi_{\vec{\pi}}-q J_{\vec{\pi}}\right)\left(w_{1}, \ldots, w_{t}\right)=\left(\psi_{\vec{\pi}}-q J_{\vec{\pi}}\right)\left(\alpha_{1} y_{1}+\beta_{1} \hat{1}, \ldots, \alpha_{t} y_{t}+\beta_{t} \hat{1}\right) \\
& =\psi_{\vec{\pi}}\left(\alpha_{1} y_{1}+\beta_{1} \hat{1}, \ldots, \alpha_{t} y_{t}+\beta_{t} \hat{1}\right)-q \operatorname{dim}\left(V_{r}\right)^{k / 2} \prod \beta_{i} . \tag{5}
\end{align*}
$$

The last equality used that $y_{i}$ is perpendicular to $\hat{1}$, so Lemma 12 implies that if $y_{i}$ appears as input to $J_{\vec{\pi}}$ then the outcome is zero no matter what the other vectors are. Thus the only non-zero term involving $J_{\vec{\pi}}$ is $J_{\vec{\pi}}(\hat{1}, \ldots, \hat{1})=\operatorname{dim}\left(V_{r}\right)^{k / 2}$. Note that $\psi(\hat{1}, \ldots, \hat{1})=\psi_{\vec{\pi}}(\hat{1}, \ldots, \hat{1})$
since the all-ones vector scaled to unit length in $V^{\otimes k_{i}}$ is the tensor product of the all-ones vector scaled to unit length in $V$. Inserting $q=\operatorname{dim}\left(V_{r}\right)^{-k / 2} \psi_{\vec{\pi}}(\hat{1}, \ldots, \hat{1})$ in (5), we obtain

$$
\begin{equation*}
\left\|\psi_{\vec{\pi}}-q J_{\vec{\pi}}\right\|=\psi_{\vec{\pi}}\left(\alpha_{1} y_{1}+\beta_{1} \hat{1}, \ldots, \alpha_{t} y_{t}+\beta_{t} \hat{1}\right)-\left(\prod \beta_{i}\right) \psi_{\vec{\pi}}(\hat{1}, \ldots, \hat{1}) . \tag{6}
\end{equation*}
$$

Now consider expanding $\psi_{\vec{\pi}}$ in (6) using linearity; the term $\left(\prod \beta_{i}\right) \psi_{\vec{\pi}}(\hat{1}, \ldots, \hat{1})$ cancels, so all terms include at least one $y_{i}$. We claim that each of these terms is small; the following claim finishes the proof, since $\left\|\psi_{\vec{\pi}}-q J_{\vec{\pi}}\right\|$ is the sum of terms each of which $o(\psi(\hat{1}, \ldots, \hat{1}))$.
Claim: If $z_{1}, \ldots, z_{i-1}, z_{i+1}, \ldots, z_{t}$ are unit length vectors, then

$$
\left|\psi_{\vec{\pi}}\left(z_{1}, \ldots, z_{i-1}, y_{i}, z_{i+1}, \ldots, z_{t}\right)\right|=o(\psi(\hat{1}, \ldots, \hat{1}))
$$

Proof. Change the ordering of $\vec{\pi}$ to an ordering $\vec{\pi}^{\prime}$ that differs from $\vec{\pi}$ by swapping 1 and $i$. Since $\psi$ is symmetric,

$$
\begin{equation*}
\psi_{\vec{\pi}}\left(z_{1}, \ldots, z_{i-1}, y_{i}, z_{i+1}, \ldots, z_{t}\right)=\psi_{\vec{\pi}^{\prime}}\left(y_{i}, z_{2}, \ldots, z_{i-1}, z_{1}, z_{i+1}, \ldots, z_{t}\right) \tag{7}
\end{equation*}
$$

Therefore proving the claim comes down to bounding $\psi_{\vec{\pi}^{\prime}}\left(y_{i}, z_{2}, \ldots, z_{i-1}, z_{1}, z_{i+1}, \ldots, z_{t}\right)$, which is a combination of Lemma 9 and Lemma 11 as follows. For the remainder of this proof, denote by $A$ the matrix $A\left[\psi_{\vec{\pi}^{\prime}}^{2 t-1}\right]$. By assumption, we have $\lambda_{2}(A)=o\left(\lambda_{1}(A)\right)$ so Lemma 11 can be applied to the matrix sequence $A$. Next we would like to show that we can use $\hat{1}$ for $x$ in the statement of Lemma 11; i.e. that $A(\hat{1}, \hat{1})=(1+o(1)) \lambda_{1}(A)$. By Lemma 9 and the assumption $\lambda_{1}(A)=(1+o(1)) \psi(\hat{1}, \ldots, \hat{1})^{2^{t-1}}$, we have

$$
\left|\psi_{\vec{\pi}^{\prime}}(\hat{1}, \ldots, \hat{1})\right|^{2^{t-1}} \leq|A(\hat{1}, \hat{1})| \leq \lambda_{1}(A)=(1+o(1)) \psi(\hat{1}, \ldots, \hat{1})^{2^{t-1}}
$$

Using the definition of $\psi_{\vec{\pi}^{\prime}}$, we have $\psi_{\vec{\pi}^{\prime}}(\hat{1}, \ldots, \hat{1})=\psi(\hat{1}, \ldots, \hat{1})$, which implies asymtotic equality through the above equation. In particular, $|A(\hat{1}, \hat{1})|=(1+o(1)) \lambda_{1}(A)$ which is the condition in Lemma 11 for $x=\hat{1}$. Lastly, to apply Lemma 11 we need a vector $y$ perpendicular to $\hat{1}$. The vector $y_{i} \otimes \cdots \otimes y_{i} \in V^{\otimes k_{i} t^{t-2}}$ is pependicular to $\hat{1}$ (in $V^{\otimes k_{i} 2^{t-2}}$ ) since $y_{i}$ itself is perpendicular to $\hat{1}$ (in $V^{\otimes k_{i}}$ ). Thus Lemma 11 implies that

$$
\begin{equation*}
|A(\underbrace{y_{i} \otimes \cdots \otimes y_{i}}_{2^{t-2}}, \underbrace{y_{i} \otimes \cdots \otimes y_{i}}_{2^{t-2}})|=o\left(\lambda_{1}(A)\right) . \tag{8}
\end{equation*}
$$

Using Lemma 9 again shows that

$$
\left|\psi_{\vec{\pi}^{\prime}}\left(y_{i}, z_{2}, \ldots, z_{i-1}, z_{1}, z_{i+1}, \ldots, z_{t}\right)\right|^{2^{t-1}} \leq|A(\underbrace{y_{i} \otimes \cdots \otimes y_{i}}_{2^{t-2}}, \underbrace{y_{i} \otimes \cdots \otimes y_{i}}_{2^{t-2}})|
$$

Combining this equation with (7) and (8) shows that $\left|\psi_{\vec{\pi}}\left(z_{1}, \ldots, z_{i-1}, y_{i}, z_{i+1}, \ldots, z_{t}\right)\right|^{2^{t-1}}=$ $o\left(\lambda_{1}(A)\right)$. By assumption, $\lambda_{1}(A)=(1+o(1)) \psi(\hat{1}, \ldots, \hat{1})^{2^{t-1}}$, completing the proof of the claim.

## $4 \mathrm{Cycle}_{4 \ell}[\pi] \Rightarrow \operatorname{Eig}[\pi]$

In this section, we prove that $\mathrm{Cycle}_{4 \ell}[\pi] \Rightarrow \operatorname{Eig}[\pi]$ for any hypergraph sequence $\mathcal{H}$ with $\left|V\left(H_{n}\right)\right|=n$ and $\left|E\left(H_{n}\right)\right| \geq p\binom{n}{k}+o\left(n^{k}\right)$. We require the following result from [16].

Proposition 13. [16, Proposition 6]Let $H$ be a $k$-uniform hypergraph, let $\vec{\pi}$ be a proper ordered partition of $k$, and let $\ell \geq 2$ be an integer. Let $\tau$ be the adjacency map of $H$. Then $\operatorname{Tr}\left[A\left[\tau_{2^{t-1}}\right]^{\ell}\right]$ is the number of labeled circuits of type $\vec{\pi}$ and length $2 \ell$ in $H$.

Propositions 3 and 13 and Lemma 10 combine to prove that $\mathrm{Cycle}_{4 \ell}[\pi] \Rightarrow \operatorname{Eig}[\pi]$ for any proper partition $\pi$ as follows.

Proof that Cycle $e_{4 \ell}[\pi] \Rightarrow$ Eig $[\pi]$. Let $\mathcal{H}=\left\{H_{n}\right\}_{n \rightarrow \infty}$ be a sequence of hypergraphs and let $\tau_{n}$ be the adjacency map of $H_{n}$. For notational convenience, the subscript on $n$ is dropped below. Throughout this proof, we use $\hat{1}$ to denote the all-ones vector scaled to unit length. Wherever we use the notation $\hat{1}$, it is the input to a multilinear map and so $\hat{1}$ denotes the all-ones vector in the appropriate vector space corresponding to whatever space the map is expecting as input. This means that in the equations below $\hat{1}$ can stand for different vectors in the same expression, but attempting to subscript $\hat{1}$ with the vector space (for example $\hat{1}_{V_{3}}$ ) would be notationally awkward.

The proof that $\mathrm{Cycle}_{4 \ell}[\pi] \Rightarrow \operatorname{Eig}[\pi]$ comes down to checking the conditions of Proposition 3. Let $\vec{\pi}$ be any ordering of the entries of $\pi$. We will show that the first and second largest eigenvalues of $A=A\left[{\underset{\tau}{\pi}}_{2^{t-1}}\right]$ are separated. Let $m=\left|E\left(C_{\pi, 4 \ell}\right)\right|=2 \ell 2^{t-1}$ and note that $\left|V\left(C_{\pi, 4 \ell}\right)\right|=m k / 2$ since $C_{\pi, 4 \ell}$ is two-regular. $A$ is a square symmetric real valued matrix, so let $\mu_{1}, \ldots, \mu_{d}$ be the eigenvalues of $A$ arranged so that $\left|\mu_{1}\right| \geq \cdots \geq\left|\mu_{d}\right|$, where $d=\operatorname{dim}(A)$. The eigenvalues of $A^{2 \ell}$ are $\mu_{1}^{2 \ell}, \ldots, \mu_{d}^{2 \ell}$ and the trace of $A^{2 \ell}$ is $\sum_{i} \mu_{i}^{2 \ell}$. Since all $\mu_{i}^{2 \ell} \geq 0$, Proposition 13 and $\mathrm{Cycle}_{4 \ell}[\pi]$ implies that

$$
\begin{equation*}
\mu_{1}^{2 \ell}+\mu_{2}^{2 \ell} \leq \operatorname{Tr}\left[A^{2 \ell}\right]=\#\left\{\text { possibly degenerate } C_{\pi, 4 \ell} \text { in } H_{n}\right\} \leq p^{m} n^{m k / 2}+o\left(n^{m k / 2}\right) \tag{9}
\end{equation*}
$$

We now verify the conditions on $\mu_{1}$ and $\mu_{2}$ in Proposition 3, and to do that we need to compute $\tau(\hat{1}, \ldots, \hat{1})$. Simple computations show that

$$
\begin{equation*}
\tau(\hat{1}, \ldots, \hat{1})=\tau_{\vec{\pi}}(\hat{1}, \ldots, \hat{1})=\frac{k!E(H)}{n^{k / 2}} \tag{10}
\end{equation*}
$$

Using that $\left|E\left(H_{n}\right)\right| \geq p\binom{n}{k}+o\left(n^{k}\right)$, Lemma 10, and $\mu_{1}^{2 \ell} \leq p^{m} n^{m k / 2}+o\left(n^{m k / 2}\right)$ from (9),

$$
\begin{equation*}
p n^{k / 2}+o\left(n^{k / 2}\right) \leq \frac{k!E(H)}{n^{k / 2}}=\tau_{\vec{\pi}}(\hat{1}, \ldots, \hat{1}) \leq\left\|\tau_{\vec{\pi}}\right\| \leq \mu_{1}^{1 / 2^{t-1}} \leq p n^{k / 2}+o\left(n^{k / 2}\right) \tag{11}
\end{equation*}
$$

This implies equality up to $o\left(n^{k / 2}\right)$ throughout the above expression, so $\tau(\hat{1}, \ldots, \hat{1})=p n^{k / 2}+$ $o\left(n^{k / 2}\right), \lambda_{1, \pi}\left(H_{n}\right)=\left\|\tau_{\vec{n}}\right\|=p n^{k / 2}+o\left(n^{k / 2}\right)$, and $\mu_{1}=p^{2^{t-1}} n^{k 2^{t-2}}+o\left(n^{k 2^{t-2}}\right)$, so $\mu_{1}=$ $(1+o(1)) \tau(\hat{1}, \ldots, \hat{1})^{2^{t-1}}$.

Insert $\mu_{1}=p^{2^{t-1}} n^{k 2^{t-2}}+o\left(n^{k 2^{t-2}}\right)$ into (9) to show that $\mu_{2}=o\left(n^{k 2^{t-2}}\right)$. Therefore, the conditions of Proposition 3 are satisfied, so

$$
\left\|\tau_{\vec{\pi}}-q J_{\vec{\pi}}\right\|=o(\tau(\hat{1}, \ldots, \hat{1}))=o\left(n^{k / 2}\right),
$$

where $q=n^{-k / 2} \tau(\hat{1}, \ldots, \hat{1})$. Using (10), $q=k!|E(H)| / n^{k}$. Thus $\left\|\tau_{\vec{\pi}}-q J_{\vec{\pi}}\right\|=\lambda_{2, \pi}\left(H_{n}\right)$ and the proof is complete.

The above proof can be extended to even length cycles in the case when $\vec{\pi}=\left(k_{1}, k_{2}\right)$ is a partition into two parts. For these $\vec{\pi}$, the matrix $A\left[\tau_{\vec{\pi}}^{2}\right]$ can be shown to be positive semidefinite since $A\left[\tau_{\vec{\pi}}^{2}\right]$ will equal $M M^{T}$ where $M$ is the matrix associated to the bilinear map $\tau_{\vec{\pi}}$. Since $A\left[\tau_{\vec{\pi}}^{2}\right]$ is positive semidefinite, each $\mu_{i} \geq 0$ so any power of $\mu_{i}$ is non-negative. For partitions into more than two parts, we don't know if the matrix $A\left[\tau_{\vec{\pi}}^{2^{t-1}}\right]$ is always positive semidefinite or not.

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