Teichmüller geometry of moduli space, I: Distance minimizing rays and the Deligne-Mumford compactification

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1 Introduction

Let S be a closed, oriented surface with a finite (possibly empty) set of points removed. In this paper we relate two important but disparate topics in the study of the moduli space $\mathcal{M}(S)$ of Riemann surfaces: Teichmüller geometry and the Deligne-Mumford compactification. We reconstruct the Deligne-Mumford compactification (as a metric stratified space) purely from the intrinsic metric geometry of $\mathcal{M}(S)$ endowed with the Teichmüller metric. We do this by first classifying (globally) geodesic rays in $\mathcal{M}(S)$ and determining precisely how pairs of rays asymptote. We construct an "iterated EDM ray space" functor, which is defined on a quite general class of metric spaces. We then prove that this functor applied to $\mathcal{M}(S)$ produces the Deligne-Mumford compactification.

Rays in $\mathcal{M}(S)$. A ray in a metric space X is a map $r:[0,\infty)\to X$ which is locally an isometric embedding. In this paper we initiate the study of (globally) isometrically embedded rays in $\mathcal{M}(S)$. Among other things, we classify such rays, determine their asymptotics, classify almost geodesic rays, and work out the Tits angles between rays. We take as a model for our study the case of rays in locally symmetric spaces, as in the work of Borel, Ji, MacPherson and others; see [JM] for a summary.

In [JM] it is explained how the continuous spectrum of any noncompact, complete Riemannian manifold M depends only on the geometry of its ends, and in some cases (e.g. when M is locally symmetric) the generalized eigenspaces can be parametrized by a compactification constructed from asymptote classes of certain rays. The spectral theory of $\mathcal{M}(S)$

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endowed with the Teichmüller metric was initiated by McMullen [Mc], who proved positivity of the lowest eigenvalue of the Laplacian. Our compactification of $\mathcal{M}(S)$ by equivalence classes of certain rays might be viewed as a step towards further understanding its spectral theory. We remark that the Teichmüller metric is a Finsler metric.

Following [JM], we will consider two natural classes of rays.

Definition 1.1 (EDM rays). A ray $r:[0,\infty)\to X$ in a metric space X is eventually distance minimizing, or EDM, if there exists t_0 such that for all $t\geq t_0$:

$$d(r(t), r(t_0)) = |t - t_0|$$

Note that, if r is an EDM ray, after cutting off an initial segment of r we obtain a globally geodesic ray, i.e. an isometric embedding of $[0, \infty) \to X$.

Definition 1.2 (ADM rays). The ray r(t) is almost distance minimizing, or ADM, if there are constants $C, t_0 \geq 0$ such that for $t \geq t_0$:

$$d(r(t), r(t_0)) \ge |t - t_0| - C$$

It is easy to check that a ray r is ADM if and only if, for every $\epsilon > 0$ there exists $t_0 \ge 0$ so that for all $t \ge t_0$:

$$d(r(t), r(t_0)) \ge |t - t_0| - \epsilon$$

As with locally symmetric manifolds, there are several ways in which a ray in $\mathcal{M}(S)$ might not be ADM: it can traverse a closed geodesic, it can be contained in a fixed compact set, or it can return to a fixed compact set at arbitrarily large times. More subtly, there are rays which leave every compact set in $\mathcal{M}(S)$ and are ADM but are not EDM; these rays "spiral" around in the "compact directions" in the cusp of $\mathcal{M}(S)$. This phenomenon does not appear in the classical case of $\mathcal{M}(T^2) = \mathbf{H}^2/\operatorname{SL}(2,\mathbf{Z})$, but it does appear in all moduli spaces of higher complexity, as we shall show.

The set of rays in $\operatorname{Teich}(S)$ through a basepoint $Y \in \operatorname{Teich}(S)$ is in bijective correspondence with the set of elements $q \in \operatorname{QD}^1(Y)$, the space of unit area holomorphic quadratic differentials q on Y (see §2 below). We now describe certain kinds of Teichmüller rays that will be important in our study.

Recall that a quadratic differential q on Y is Strebel if all of its vertical trajectories are closed. In this case Y decomposes into a union of cylinders. Each cylinder is swept out by vertical trajectories of the same length. q is said to be mixed Strebel if it contains at least one cylinder of closed trajectories.

Definition 1.3 ((Mixed) Strebel rays). A ray in $\mathcal{M}(S)$ is a (mixed) Strebel ray if it is the projection to $\mathcal{M}(S)$ of a ray in $\mathrm{Teich}(S)$ corresponding to a pair (Y,q) with q a (mixed) Strebel differential on Y.

Our first main result is a classification of EDM rays and ADM rays in moduli space $\mathcal{M}(S)$.

Theorem 1.4 (Classification of EDM rays in $\mathcal{M}(S)$). Let r be a ray in $\mathcal{M}(S)$. Then

- 1. r is EDM if and only if it is Strebel.
- 2. r is ADM if and only if it is mixed Strebel.

One of the tensions arising from Theorem 1.4 is that for any $\epsilon > 0$, there exist very long local geodesics γ between points x, y in $\mathcal{M}(S)$ which are only ϵ longer than any (global) geodesic from x to y. As distance in $\mathcal{M}(S)$ is difficult to compute precisely, the question arises as to how such "fake global geodesics" γ can be distinguished from true global geodesics. This is done in §3.2. The idea is to use the input data of being non-Strebel to build by hand a map whose log-dilatation equals the length of γ , but which has nonconstant pointwise quasiconformal dilatation. By Teichmüller's uniqueness theorem, since the actual Teichmüller map from x to y has constant pointwise dilatation, this dilatation, and thus the length of the Teichmüller geodesic connecting x to y, is strictly smaller than the length of γ .

We also determine finer information about EDM rays. In Section 3.4 we determine the limiting asymptotic distance between EDM rays: it equals the Teichmüller distance of their endpoints in the "boundary moduli space" (see Theorem 3.9 below). This precise behavior of rays in $\mathcal{M}(S)$ lies in contrast to the behavior of rays in the Teichmüller space of S, which themselves may not even have limits. Theorem 3.9 is crucial for our reconstruction of the Deligne-Mumford compactification. In Section 5.3 we compute the Tits angle of any two rays, showing that only 3 possible values can occur. This result contrasts with the behavior in locally symmetric manifolds, where a continuous spectrum of Tits angles can occur.

Reconstructing the topology of Deligne-Mumford. Deligne-Mumford [DM] constructed a compactification $\overline{\mathcal{M}(S)}^{DM}$ of $\mathcal{M}(S)$ whose points are represented by conformal structures on noded Riemann surfaces. They proved that $\overline{\mathcal{M}(S)}^{DM}$ is a projective variety. As such, $\overline{\mathcal{M}(S)}^{DM}$ as a topological space comes with a natural stratification: each stratum is a product of moduli spaces of surfaces of lower complexity. We will equip each moduli space with the Teichmüller metric, and the product of moduli spaces with the sup metric. In this way $\overline{\mathcal{M}(S)}^{DM}$ has the structure of a metric stratified space, i.e. a stratified space with a metric on each stratum (see §4 below). We note that $\overline{\mathcal{M}(S)}^{DM}$ was also constructed topologically by Bers in [Be].

In Section 4 we construct, for any geodesic metric space X, a space \overline{X}^{ir} of X, called the *iterated EDM ray space* associated to X. This space comes from considering asymptote classes of EDM rays, endowing the set of these with a natural metric, and then considering

asymptote classes of EDM rays on this space, etc. The space \overline{X}^{ir} has the structure of a metric stratified space.

Theorem 1.5. Let S be a surface of finite type. Then there is a strata-preserving homeomorphism $\overline{\mathcal{M}(S)}^{ir} \to \overline{\mathcal{M}(S)}^{\mathrm{DM}}$ which is an isometry on each stratum.

Thus, as a metric stratified space, $\overline{\mathcal{M}(S)}^{DM}$ is determined by the intrinsic geometry of $\mathcal{M}(S)$ endowed with the Teichmüller metric. The following table summarizes a kind of dictionary between purely (Teichmüller) metric properties of $\mathcal{M}(S)$ on the one hand, and purely combinatorial/analytic properties on the other. Each of the entries in the table is proved in this paper.

PURELY METRIC	ANALYTIC/COMBINATORIAL
EDM ray in $\mathcal{M}(S)$	Strebel differential
ADM ray in $\mathcal{M}(S)$	mixed Strebel differential
isolated EDM ray in $\mathcal{M}(S)$	one-cylinder Strebel differential
asymptotic EDM rays in $\mathcal{M}(S)$	modularly equivalent Strebel differentials
	with same endpoint
iterated EDM ray space of $\mathcal{M}(S)$	Deligne-Mumford compactification $\overline{\mathcal{M}(S)}^{DM}$
rays of rays of \cdots of rays (k times)	level k stratum of $\overline{\mathcal{M}(\mathrm{S})}^{\mathrm{DM}}$
Tits angle 0	pairs of combinatorially equivalent
	Strebel differentials
Tits angle 1	pairs of Strebel differentials with
	*
	disjoint cylinders

Finally, in Section 5.4, we consider Minsky's Product Theorem [Mi1]. This theorem gives, up to an additive constant D > 0, a formula for the Teichmüller distance in the thin part of Teichmüller space. In Theorem 5.4 we show that for many pairs of sequences of points, $D \to 0$ as one exits the cusp of $\mathcal{M}(S)$.

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2 Teichmüller geometry and extremal length

In this section we quickly explain some basics of the Teichmüller metric and quadratic differentials. We also make some extremal length estimates which will be used later. The

notation fixed here will be used throughout the paper.

Throughout this paper S will denote a surface of finite type, by which we mean a closed, oriented surface with a (possibly empty) finite set of points deleted. We call such deleted points punctures. The Teichmüller space Teich(S) is the space of equivalence classes of marked conformal structures (f, X) on S, where two markings $f_i : S \to X_i$ are equivalent if there is a conformal map $h : X_1 \to X_2$ with f_2 homotopic to $h \circ f_1$. The Teichmüller metric on Teich(S) is the metric defined by

$$d_{\mathrm{Teich}(S)}((X,g),(Y,h)) := \frac{1}{2}\inf\{\log K(f): f: X \to Y \text{ is homotopic to } h \circ g^{-1}\}$$

where f is quasiconformal and

$$K(f) := \operatorname{ess} - \sup_{x \in S} K_x(f) \ge 1$$

is the quasiconfromal dilatation of f, where

$$K_x(f) := rac{|f_z(x)| + |f_{\overline{z}}(x)|}{|f_z(x)| - |f_{\overline{z}}(x)|}$$

is the pointwise quasiconformal dilatation at x. We also use the notation $d_{\text{Teich}(S)}(X, Y)$ with the markings implied. The mapping class group Mod(S) is the group of homotopy classes of orientation-preserving homeomorphisms of S. This group acts properly discontinuously and isometrically on $(\text{Teich}(S), d_{\text{Teich}(S)})$, and so the quotient

$$\mathcal{M}(S) = \operatorname{Teich}(S) / \operatorname{Mod}(S)$$

has the induced metric. $\mathcal{M}(S)$ is the moduli space of (unmarked) Riemann surfaces, or what is the same thing, conformal structures on S.

2.1 Quadratic differentials and Teichmüller rays

Quadratic differentials and measured foliations. Let S be a surface of finite type, and let $X \in \text{Teich}(S)$. Recall that a *(holomorphic) quadratic differential q* on X is a tensor locally given by $q = q(z)dz^2$, where q(z) is holomorphic. Let QD(X) denote the space of holomorphic quadratic differentials on X. Any $q \in QD(X)$ determines a singular Euclidean metric $|q(z)||dz|^2$, with the finitely many singular points corresponding to the zeroes of q. The total area of X in this metric is finite, and is denoted by ||q||, which is a norm on QD(X). We denote by $QD^1(X)$ the set of elements $q \in QD(X)$ with ||q|| = 1.

An element $q \in \mathrm{QD}(X)$ determines a pair of transverse measured foliations $\mathcal{F}_h(q)$ and $\mathcal{F}_v(q)$, called the *horizontal and vertical foliations* for q. The leaves of these foliations are given by setting the real part (resp. imaginary part) of q equal to a constant. In

a neighborhood of a nonsingular point, there are natural coordinates z = x + iy so that the leaves of \mathcal{F}_h are given by y = const., the leaves of \mathcal{F}_v are given by x = const., and the transverse measures are |dy| and |dx|. The foliations \mathcal{F}_h and \mathcal{F}_v have the zero set of q as their common singular set, and at each zero of order k they have a (k+2)-pronged singularity, locally modelled on the singularity at the origin of $z^k dz^2$. The leaves passing through a singularity are the singular leaves of the measured foliation. A saddle connection is a leaf joining two (not necessarily distinct) singular points. The union of the saddle connections of the vertical foliation is called the critical graph $\Gamma(q)$ of q.

The components $X \setminus \Gamma(q)$ are of two types: cylinders swept out by vertical trajectories (i.e. leaves of \mathcal{F}_v) of equal length, and *minimal components* where every leaf is dense.

Teichmüller maps and rays. Teichmüller's Theorem states that, given any $X,Y \in \operatorname{Teich}(S)$, there exists a unique (up to translation in the case when S is a torus) quasiconformal map f, called the Teichmüller map, realizing $d_{\operatorname{Teich}(S)}(X,Y)$. The Beltrami coefficient $\mu:=\frac{\overline{\partial}f}{\partial f}$ is of the form $\mu=k\frac{\overline{q}}{|q|}$ for some $q\in\operatorname{QD}^1(X)$ and some k with $0\leq k<1$. In natural local coordinates given by q and a quadratic differential on Y, we have $f(x+iy)=Kx+\frac{1}{K}iy$, where $K=K(f)=\frac{1+k}{1-k}$. Thus f dilates the horizontal foliation by K and the vertical foliation by 1/K.

Any $q \in \mathrm{QD}^1(X)$ determines a geodesic ray $r = r_{(X,q)}$ in $\mathrm{Teich}(S)$, called the *Teichmüller* ray based at X in the direction of q. The ray r is given by the complex structures determined by the quadratic differentials q(t) obtained by multiplying the transverse measures of $\mathcal{F}_h(q)$ and $\mathcal{F}_v(q)$ by $\frac{1}{K} = e^{-t}$ and $K = e^t$, respectively, for t > 0. To summarize, for each $X \in \mathrm{Teich}(S)$, there is a bijective correspondence between the set of rays in $\mathrm{Teich}(S)$ based at X and the set of elements of $\mathrm{QD}^1(X)$.

Finally, we note that any ray in $\mathcal{M}(S)$ is the image of a ray in $\mathrm{Teich}(S)$ under the natural quotient map

$$\operatorname{Teich}(S) \to \mathcal{M}(S) = \operatorname{Teich}(S) / \operatorname{Mod}(S).$$

2.2 Extremal length and Kerckhoff's formula

Kerckhoff [Ke] discovered an elegant and useful way to compute Teichmüller distance in terms of extremal length, which is a conformal invariant of isotopy classes of simple closed curves. We now describe this, following [Ke].

Recall that a conformal metric on a Riemann surface X is a metric which is locally of the form $\rho(z)|dz|$, where ρ is a non-negative, real-valued function on X. A conformal metric determines a length function ℓ_{ρ} , which assigns to each (isotopy class of) simple closed curve γ the infimum $\ell_{\rho}(\gamma)$ of the lengths of all curves in the isotopy class, where length is measured with respect to the conformal metric. We denote the area of X in a conformal metric given

by a function ρ by $\text{Area}_{\rho}(X)$, or Area_{ρ} when X is understood.

By cylinder we will mean the surface $S^1 \times [0,1]$, endowed with a conformal metric. Recall that any cylinder C is conformally equivalent to a unique annulus of the form $\{z \in \mathbf{C} : 1 \le |z| \le r\}$. The number $(\log r)/2\pi$ will be called the modulus of C, denoted $\mathrm{mod}(C)$. A cylinder in X is an embedded cyclinder C in X, endowed with the conformal metric induced from the conformal metric on X. There are two equivalent definitions of extremal length, each of which is useful.

Definition 2.1 (Extremal length). Let X be a fixed Riemann surface, and let γ be an isotopy class of simple closed curves on X. The extremal length of γ in X, denoted by $\operatorname{Ext}_X(\gamma)$, or $\operatorname{Ext}(\gamma)$ when X is understood, is defined to be one of the following two equivalent quantities:

Analytic definition:

$$\operatorname{Ext}(\gamma) := \sup_{\rho} \ell_{\rho}(\gamma)^2 / \operatorname{Area}_{\rho}$$

where the supremum is over all conformal metrics on X of finite positive area.

Geometric definition:

$$\operatorname{Ext}(\gamma) := \sup\{\frac{1}{\operatorname{mod}(C)} : C \text{ is a cylinder with core curve isotopic to } \gamma\}$$

As pointed out by Kerckhoff in [Ke], and as we will see throughout the present paper, the analytic definition is useful for finding lower bounds for $\text{Ext}(\gamma)$, while the geometric definition is useful for finding upper bounds.

Theorem 2.2 (Kerckhoff [Ke], Theorem 4). Let S be any surface of finite type, and let X, Y be any two points of Teich(S). Then

$$d_{\mathrm{Teich}(S)}(X,Y) = \frac{1}{2}\log\left[\sup_{\gamma} \frac{\mathrm{Ext}_X(\gamma)}{\mathrm{Ext}_Y(\gamma)}\right] \tag{1}$$

where the supremum is taken over all isotopy classes of simple closed curves γ on S.

Remark. The definition of extremal length is easily extended to measured foliations. The density of simple closed curves in the space $\mathcal{MF}(S)$ of measured foliations on S allows us to replace the right hand side of (1) by the supremum taken over all $\gamma \in \mathcal{MF}(S)$.

2.3 Extremal length estimates along Strebel rays

Let (X,q) be a Riemann surface $X \in \text{Teich}(S)$ with Strebel differential $q \in \text{QD}(X)$, and let $r = r_{(X,q)}$ be the corresponding Strebel ray. Our goal in this subsection is to estimate the extremal length $\text{Ext}_{r(t)}(\beta)$ of an arbitrary (isotopy class of) simple closed curve β as the underlying Riemann surface moves along the ray r. The following estimates are due to Kerckhoff [Ke]. We include proofs here for completeness, and because these estimates are so essential for this paper.

The setup will be as follows. Let C_i , $1 \le i \le n$ be the cylinders of the Strebel differential q, and for each i let α_i denote the homotopy class of the core curve of C_i . Let $a_i(t)$ denote the q(t)-length of α_i and let $b_i(t)$ denote the q(t)-height of C_i . Let $M_i(t) = \text{mod}(C_i) = b_i(t)/a_i(t)$ be the modulus. Note that on the Riemann surface r(t) we have

$$a_i(t) = e^{-t}a_i(0)$$

and the height $b_i(t)$ of the cylinder C_i satisfies

$$b_i(t) = e^t b_i(0).$$

Lemma 2.3. With notation as above, the following hold:

- 1. $\lim_{t\to\infty} e^{2t} M_i(0) Ext_{r(t)}(\alpha_i) = 1$.
- 2. There is a constant c > 0 such that if $i(\beta, \alpha_i) = 0$ for all i and β is not isotopic to any of the α_i , then for all t

$$Ext_{r(t)}(\beta) \geq c.$$

3. There is a constant c > 0 such that if β crosses C_i then

$$Ext_{r(t)}(\beta) \ge ce^{2t}$$
.

Proof. To prove Statement (1) we recall that the geometric definition of extremal length says that

$$\operatorname{Ext}_{r(t)}(\alpha_i) = \sup \frac{1}{\operatorname{mod}(A)},$$

where the supremum is taken over all cylinders $A \subset r(t)$ homotopic to α_i . Statement 1 is immediate in the case that m=1, for then by Theorem 20.4(3) of [St], taken with i=1, the modulus of a one-cylinder Strebel differential realizes the supremum in the geometric definition. In that case the limit in Statement 1 is actually an equality for each t. Thus assume m>1. On r(t), the cylinder C_i has modulus $[e^{2t}b_i(0)/a_i(0)]=e^{2t}M_i(0)$, giving the bound

$$\operatorname{Ext}_{r(t)}(\alpha_i) \le \frac{e^{-2t}}{M_i(0)}.$$

We now give a lower bound. We can realize the surface r(t) by cutting along the core curves of the cylinders, inserting cylinders, and regluing. Rescaling by e^{2t} the flat metric induced by q(t) gives a flat metric $\rho(t)$ of area e^{2t} for which the core curves have constant length $a_i(0)$ and height $e^{2t}b_i(0)$. Choose a constant b such that $b > a_i(0)$, and for t_0 sufficiently large, choose a fixed neighborhood Nbhd (C_i) of C_i on $r(t_0)$ such that

$$d_{\rho(t)}(C_i, \partial \operatorname{Nbhd}(C_i)) = b.$$

For some fixed B > 0 we have

$$\operatorname{area}_{\rho(t)}(\operatorname{Nbhd}(C_i)\setminus C_i)=B.$$

We may think of Nbhd(C_i) \ C_i as a subset of r(t) for $t \geq t_0$. Define a conformal metric $\sigma_i(t)$ on r(t) as follows. It is given by $\rho(t)$ on C_i . On Nbhd(C_i) \ C_i it is given by the metric $\rho(t_0)$, and on r(t) \ Nbhd(C_i) it is given by $\delta\rho(t)$ for some $\delta > 0$. With respect to the metric $\sigma_i(t)$ we then have

$$d_{\sigma_i(t)}(C_i, \partial \operatorname{Nbhd}(C_i)) = b$$

and

$$Area_{\sigma_i(t)} \le B + \delta e^{2t} + e^{2t} a_i(0) b_i(0).$$

Since the distance across $Nbhd(C_i) \setminus C_i$ is at least $b \geq a_i(0)$, it is easy to see that

$$\ell_{\sigma_i(t)}(\alpha_i) = a_i(0).$$

Putting the estimates on lengths and areas together, it follows that given any $\epsilon > 0$, we may choose $\delta > 0$ so that for t large enough,

$$\operatorname{Ext}_{r(t)}(\alpha_i) \ge \frac{\ell_{\sigma_i(t)}^2(\alpha_i)}{A_{\sigma_i(t)}} \ge (1 - \epsilon) \frac{e^{-2t}}{M_i(0)}.$$

Putting this lower bound together with the upper bound we have proved (1).

For the proof of (2), take a fixed neighborhood N of the component of the critical graph Γ that contains β such that the distance across N is at least $\min_i a_i(0)$, the lengths of the core curves of the cylinders on the base surface r(0). Again we may consider N as a subset of r(t) for all $t \geq 0$. We put a conformal metric $\sigma(t)$ on r(t) which is given by $\rho(t) = e^{2t}q(t)$ on N and q(t) on $r(t) \setminus N$. For some fixed B > 0 we have

$$Area_{\sigma(t)} \leq B$$
.

Now any geodesic representative of β that enters $r(t) \setminus N$ must bound a disc with a core curve of C_i , and can be shortened to lie entirely inside N. Thus its geodesic representative lies in the critical graph and so there is a b such that

$$\ell_{\sigma(t)}(\beta) \geq b.$$

The lower bound now follows from the analytic definition of extremal length.

The proof of (3) follows by using the given metric q(t) in the analytic definition of extremal length. \diamond

3 EDM and ADM rays in moduli space

In this section we classify EDM and ADM rays in moduli space, giving a proof of Theorem 1.4. We then determine, in §3.4, when two EDM rays are asymptotic.

3.1 Strebel rays are EDM

Our goal in this subsection is to prove one direction of Theorem 1.4, namely that if (X, q) is Strebel then the ray $r_{(X,q)}$ in $\mathcal{M}(S)$ is eventually distance minimizing. In other words, we must find $t_0 \geq 0$ so that

$$d_{\text{Teich}(S)}(r(t), r(t_0)) \le d_{\text{Teich}(S)}(\phi(r(t_0)), r(t))$$
(2)

for all $t \ge t_0$ and for every $\phi \in \text{Mod}(S)$. In fact we will prove that the inequality in (2) is strict for $t > t_0$.

Remark. Note that while any two nonseparating curves on S can be taken to each other via some element of Mod(S), Strebel rays along cylinders with nonseparating core curves, based at the same $Y \in Teich(S)$, project to different rays in $\mathcal{M}(S)$. Indeed, given any point $X \in \mathcal{M}(S)$, there are countably infinitely many Strebel rays in $\mathcal{M}(S)$ based at X, even though there are [g/2] + 1 topological types of simple closed curves on S.

Let $\alpha_1, \ldots, \alpha_p$ denote the core curves of the cylinders $\{C_i\}$ in the cylinder decomposition of (X, q). By Lemma 2.3, the extremal length of curves β with $i(\beta, \alpha_i) = 0$ for each $1 \le i \le p$ and not homotopic to any α_i remain bounded below by some d > 0. By Lemma 2.3 the extremal length of any curve β with $i(\beta, \alpha_i) > 0$ for some i tends to ∞ as $t \to \infty$. Choose t_0 big enough so that each of the following holds:

1. If $i(\beta, \alpha_i) > 0$ for some i then $\operatorname{Ext}_{r(t)}(\beta) \geq d$ for $t \geq t_0$.

- 2. $e^{2t_0} > 2 \max_i(\frac{M_i}{d})$, where M_i is the modulus of the cylinder C_i
- 3. For $t \geq t_0$, $\operatorname{Ext}_{r(t)}(\alpha_i) \leq 2e^{-2t}M_i$. (This can be done by Lemma 2.3).

Let ϕ be any nontrivial element of Mod(S). Suppose first that $\phi^{-1}(\alpha_i) = \beta \notin \{\alpha_j\}$ for some i. By Theorem 2.2 we have for $t > t_0$:

$$d_{\text{Teich}(S)}(\phi(r(t_0)), r(t)) \geq \frac{1}{2} \log \frac{\text{Ext}_{\phi(r(t_0))}(\alpha_i)}{\text{Ext}_{r(t)}(\alpha_i)}$$

$$= \frac{1}{2} \log \frac{\text{Ext}_{r(t_0)}(\beta)}{\text{Ext}_{r(t)}(\alpha_i)}$$

$$\geq \frac{1}{2} \log \frac{d}{2e^{-2t}M_i}$$

$$> \frac{1}{2} \log \frac{e^{2t}}{e^{2t_0}} = t - t_0 = d_{\text{Teich}(S)}(r(t), r(t_0))$$

Thus we may assume that ϕ preserves $\{\alpha_i\}$ as a set. Consider the special case when $\phi(\alpha_i) = \alpha_i$ for each i. This assumption implies that ϕ^{-1} preserves the vertical foliation $\mathcal{F}_v(q)$ of q, as a measured foliation. Then

$$d_{\text{Teich}(S)}(\phi(r(t_0)), r(t) \ge \frac{1}{2} \log \frac{\text{Ext}_{\phi(r(t_0))}(\mathcal{F}_v(q))}{\text{Ext}_{r(t)}(\mathcal{F}_v(q))} = \frac{1}{2} \log \frac{\text{Ext}_{r(t_0)}(\mathcal{F}_v(q))}{\text{Ext}_{r(t)}(\mathcal{F}_v(q))} = t - t_0$$
 (3)

and we are again done in this case. The leftmost inequality follows from the remark after Theorem 2.2.

We remark that the inequality (3) is strict. This is because equality of the leftmost terms occurs if and only if $\mathcal{F}_v(q)$ is the vertical foliation of the quadratic differential defining the Teichmuller map from $\phi(r(t_0))$ to r(t). However, $\mathcal{F}_v(q)$ is the vertical foliation of the quadratic differential of the Teichmuller map from $r(t_0)$ to r(t), and so it cannot be the former since ϕ is assumed to be nontrivial.

Finally, consider the general case of ϕ preserving $\{\alpha_i\}$ as a set. Let k be the smallest integer such that $\phi^k(\alpha_i) = \alpha_i$ for all i. If the desired result is not true there is a sequence of times $t_0 < t_1 < \ldots < t_k$ such that

$$d_{\mathrm{Teich}(S)}(r(t_{i-1}),\phi(r(t_i))) < d_{\mathrm{Teich}(S)}(r(t_{i-1}),r(t_i)).$$

Since ϕ acts as an isometry of Teich(S), applications of the triangle inequality give

$$d_{\text{Teich}(S)}(r(t_0), \phi^k(r(t_k))) < d_{\text{Teich}(S)}(r(t_0), r(t_k)).$$

But ϕ^k fixes each α_i , and we have a contradiction to the previous assertion.

3.2 Every EDM ray is Strebel

In this subsection we prove the other direction of Theorem 1.4, namely that if a ray $r_{(X,q)}$: $[0,\infty) \to \mathcal{M}(S)$ is EDM then (X,q) is Strebel. The idea of the proof is explained in the introduction above. Since r is EDM, we can change basepoint and assume that r is (globally) isometrically embedded. We henceforth assume this.

Recall that for each $t \geq 0$ the ray $r = r_{(X,q)}$ determines the following data: the Riemann surface $r(t) \in \mathcal{M}(S)$, the quadratic differential $q(t) \in \mathrm{QD}^1(r(t))$, and the vertical foliation $\mathcal{F}_v(q(t))$ for the quadratic differential q(t). Let $\Gamma(t)$ denote the critical graph of q(t), so that $\Gamma(t)$ is the union of the vertical saddle connections of q(t). Note that $\Gamma(t)$ may be empty.

For any quadratic differential q on a Riemann surface X, let Σ denote the set of zeroes of q. We define the diameter of X (in the q-metric d_q), denoted diam(X), to be

$$\operatorname{diam}(X) := \sup_{x \in X} d_q(x, \Sigma).$$

Now suppose that the ray $r = r_{(X,q)}$ is not Strebel. This assumption implies that there is some subsurface $Y(t) \subseteq r(t)$ which contains some leaf of $\mathcal{F}_v(q(t))$ which is dense in Y(t).

Step 1 (Delaunay triangulations):

Proposition 3.1. There is a triangulation $\Delta(t)$ on r(t) with the following properties:

- 1. The vertices of $\Delta(t)$ lie in the zero set of q(t).
- 2. The edges of $\Delta(t)$ are saddle connections of q(t).
- 3. For t large enough, every edge of the vertical critical graph $\Gamma(t)$ is an edge of $\Delta(t)$.
- 4. There is a function c(t) with $c(t) \to \infty$ as $t \to \infty$ so that every triangle in $\Delta(t)$ whose interior is contained in some minimal component Y, can be inscribed in a circle of radius at most $e^t/c(t)$.

Proof. The triangulation $\Delta(t)$ will be the *Delaunay triangulation* $\Delta(t)$ constructed by Masur-Smillie in §4 of [MS]. In particular, $\Delta(t)$ automatically satisfies (1) and (2). We now claim something very special about $\Delta(t)$.

Lemma 3.2. There is a function c(t) with $\lim_{t\to\infty} c(t) = \infty$ with the following property: the shortest saddle connection $\beta(t)$ of the quadratic differential q(t) on r(t), whose endpoints lie in $\overline{Y} \cap \Sigma$, and whose interior lies in Y, has length at least $c(t)e^{-t}$.

Proof. [of Lemma 3.2] Denote by $|\cdot|_t$ the length function associated to flat metric on r(t) induced by q(t). For an arc α , we denote by $|\alpha|_t^{\text{vert}}$ (resp. $|\alpha|_t^{\text{horiz}}$) the length of α as measured with respect to the transverse measure |dy| on $\mathcal{F}_h(q(t))$ (resp. |dx| on $\mathcal{F}_v(q(t))$).

We claim that there is a constant D such that $|\beta(t)|_t \leq D$. To prove the claim, consider an edge E of the Delaunay triangulation $\Delta(t)$ with $E \cap Y \neq \emptyset$. First suppose $|E|_t \leq s =$: $2\sqrt{2/\pi}$. If $E \subset Y$ then take D = s and we are done. If E is not contained in Y, then it crosses some edge α of $\Gamma(t)$. We remind the reader that, as we move out along r(t), the horizontal lengths are expanded by e^t and the vertical length are contracted by e^{-t} . Thus we have the equation

$$|\alpha|_t = e^{-t}|\alpha|_0. (4)$$

But then we can take some subsegment of E, together with a union of at most two subsegments of $\Gamma(t)$, to give a nontrivial homotopy class of arc with endpoints in $\overline{Y} \cap \Sigma$ and interior contained in Y. The geodesic representative $\beta(t)$ in this homotopy class has length bounded above by the length of E plus the length of $\Gamma(t)$, which for large enough t is less than D = s + 1, and we are done.

We are now reduced to the case where E has length at least s. By Proposition 5.4 of [MS], E must cross some flat cyclinder C in r(t) whose height is greater than its circumference. If $C \subset Y$, then since Y has area at most 1, the circumference is at most 1, and so taking $\beta(t)$ to be the circumference, we have $|\beta(t)|_t \leq 1$. If C is not contained in Y, then C crosses the critical graph $\Gamma(t)$. Thus the height of C is bounded, as in (4). Thus the circumference is bounded as well. An argument similar to the previous paragraph then provides $\beta(t)$, and the claim is proved.

We now continue with the proof of the lemma. We have

$$|\beta(t)|_t \ge |\beta(t)|_t^{\text{horiz}} = e^t |\beta(t)|_0^{\text{horiz}}.$$

Since $|\beta(t)|_t$ is bounded, we must have $|\beta(t)|_0^{\text{horiz}} \to 0$ as $t \to \infty$. Since Y is assumed to be minimal, there are no vertical saddle connections in Y, and so $|\beta(t)|_0^{\text{horiz}} > 0$. Because the set of holonomy vectors of saddle connections is a discrete subset of \mathbf{R}^2 for a fixed flat structure (see, e.g, [HS]), this forces $|\beta(t)|_0^{\text{vert}} \to \infty$ as $t \to \infty$. Now

$$|\beta(t)|_t \ge |\beta(t)|_t^{\text{vert}} = e^{-t}|\beta(t)|_0^{\text{vert}}.$$

Thus the desired inequality holds with $c(t) = |\beta(t)|_0^{\text{vert}}$. \diamond

We continue with the proof of the proposition.

For t sufficiently large, by Lemma 3.2 the segments of $\Gamma(t)$ are the shortest saddle connections on q(t). Now since these segments are all vertical, given such a segment α , the midpoint p of α has the property that the two endpoints of α realize the distance from p to Σ . Thus, by construction of the Delaunay triangulation (see §4 of [MS]), the entire segment α lies in $\Delta(t)$. This proves (3).

We now prove (4). By (3), no edge of the triangulation crosses $\Gamma(t)$, so any 2-cell that intersects a minimal component Y is contained in that minimal component. By Theorem 4.4 of [MS], every point in Y is contained in a unique Delaunay cell isometric to a polygon inscribed in a circle of radius $\leq \operatorname{diam}(Y)$. It therefore remains to bound $\operatorname{diam}(Y)$.

If diam(Y) > 2s, then there is a cylinder C whose height is at least s. As we have seen above, such a cylinder must be contained in Y, as it cannot cross $\Gamma(t)$ for sufficiently large t. But Lemma 3.2 gives that the circumference of C is at least $c(t)e^{-t}$, and since r(t) has unit area, the height of C is at most $e^t/c(t)$, and there the diameter is at most $(e^t/2c(t)) + 1$ (the second term coming from a bound on the length of the circumference of C). \diamond

We now return to the proof that EDM rays are Strebel. We will argue by contradiction and assume it is not Strebel. Thus there is at least one minimal component in the complement of the critical graph. Let C_1, \ldots, C_r be the (possibly empty) collection of vertical cylinders of q_0 . By the cylinder data for q_0 we mean the following three pieces of data:

- 1. The isometry type of each C_i .
- 2. The singularities on ∂C_i .
- 3. The lengths of saddle connections between these singularities.
- 4. The combinatorics of the gluings of these edges.

A triangulation of a pair (X, q) where X is a Riemann surface and q is a quadratic differential on X is a triangulation in the usual sense, all of the vertices of triangles have to be singularities of q, and every edge is a saddle connection (we are also allowing loops).

Proposition 3.3. Let (r_0, q_0) be given with (possibly empty) cylinder data. There exist finitely many triangulations T_1, \ldots, T_n of (r_0, q_0) , each with the same cylinder data as (r_0, q_0) , such that for any combinatorial type of triangulation Δ that appears as the Delaunay triangulation $\Delta(t_n)$ for a sequence $t_n \to \infty$, there exists some T_i combinatorially equivalent to Δ , with the same cylinder data.

Proof. For any such Δ , choose $t_1 \geq 0$ to be the smallest time for which $\Delta(t_1)$ appears in its combinatorial equivalence class. Now let T_1 be the pullback of $\Delta(t_1)$ by the Teichmuller map $f: r(0) \to r(t_1)$. We remark that T_1 is not necessarily Delaunay with respect to the flat structure given by q(0).

We now do this for each new combinatorial class that appears along r(t). There are only finitely many such T_i since there are only finitely many combinatorial types of triangulations with a fixed number of vertices and edges. \diamond

Step 2 (Building the fake Teichmüller map): Given r(t), we will build a very efficient map ψ from some r(0) to r(t). We first need the following lemma about Euclidean triangles.

Lemma 3.4 (Euclidean triangle lemma). Fix a triangle T_0 in the Euclidean plane. Then there is a constant b, depending only on T_0 , with the following property: for any other Euclidean triangle T whose shortest side has length at least ϵ , such that each side has length at most R, and which can be inscribed in a circle of radius R, there is an affine map from T_0 to T which has quasiconformal dilatation at most bR/ϵ .

Proof. Let p_i , i = 1, 2, 3 the vertices of T on the circle and assume $\overline{p_1p_2}$ is the shortest side with length $a_1 \geq \epsilon$, $\overline{p_1, p_3}$ is the longest side with length $a_3 \leq R$. Let p_0 the center of the circle. Let θ the angle at p_3 of the T. We claim that

$$\sin(\theta) = \frac{a_1}{2R} \ge \frac{\epsilon}{2R}.$$

Let ψ_1 be the angle at p_0 of the isoceles triangle with vertices at p_0, p_1, p_2 . Let ψ_2 the angle at p_0 of the isoceles triangle with vertices p_0, p_2, p_3 . Let ψ the angle at p_3 of the isoceles triangle with vertices p_0, p_1, p_3 . Since this triangle is isoceles, we have

$$2\psi = (\pi - (\psi_1 + \psi_2)).$$

Since the triangle with vertices at p_0, p_2, p_3 is isoceles, we have

$$2(\psi + \theta) = \pi - \psi_2.$$

Subtracting we get

$$\theta = \psi_1/2$$
,

proving the claim. Similarly we have θ' , the angle of T at p_1 , is given by

$$\sin(\theta') = \frac{a_2}{2R} \ge \sin(\theta),$$

where a_2 is length of the side $\overline{p_2p_3}$. Now let h be the height of the triangle T with vertex p_2 and opposite side length a_3 . dividing T into a pair of triangles T_1, T_2 with bases x_1, x_2 and angles θ, θ' . Since $\theta' \geq \theta$ we have

$$x_2/h \le x_1/h = \cot(\theta) \le 1/\sin(\theta) \le \frac{2R}{\epsilon}.$$

Thus if we double the triangles we find their moduli are bounded by $\frac{2R}{\epsilon}$ and so the affine map to a standard isoceles right triangle has dilatation bounded in terms of $\frac{R}{\epsilon}$. \diamond

Proposition 3.5. For t sufficiently large there exists a map $\psi : r(0) \to r(t)$ which is at most a e^{2t} -quasiconformal map and which is not the Teichmüller map.

Proof. For any t sufficiently large, choose T_i such that the (r(0), q(0)) triangulation T_i described in Proposition 3.3 is combinatorially equivalent to the Delaunay triangulation $\Delta(t)$ on r(t), say via a homeomorphism $h: r(0) \to r(t)$.

Let a be the length of the shortest vertical saddle connection of (r(0), q(0)). We now build the map $\psi : r(0) \to r(t)$. On each vertical cylinder, ψ will be the linear map of least quasiconformal dilatation, which is e^{2t} . Notice this is the map that agrees with the Teichmuller map $f : r(0) \to r(t)$ on the cylinder. Extend the map to the obvious linear map on the critical graph $\Gamma(0)$. We are left with having to define ψ on the nonempty collection of complementary minimal components of $r(0) \setminus \Gamma(0)$.

The homeomorphism h gives a bijective mapping between the set of triangles of T_i and those of $\Delta(t)$. For each triangle P of T_i , each of P and h(P) has a given Euclidean structure. Define ψ to be the unique affine map wihich identifies edges in the same combinatorial way as h does.

Let a be the length of the shortest edge in the critical graph Γ . By property (4) of Proposition 3.1 applied to $\Delta(t)$, we can apply Lemma 3.4 with $\epsilon \geq ae^{-t}$ and $R = e^t/c(t)$ to conclude that on the union of the interiors of the triangles which are not in any vertical cylinder, the pointwise quasiconformal dilatation is at most

$$\frac{e^t b}{ac(t)e^{-t}} = \frac{be^{2t}}{ac(t)}.$$

Note that since there are only finitely many T_i , the constant b is universal.

Since $c(t) \to \infty$, this number can be taken to be smaller than e^{2t} . Note that with quasiconformal maps we only need to check dilatation on a set of full measure, since quasiconformal dilatation is an L^{∞} norm.

Thus the (global) dilatation $K(\psi)$, as a supremum of the dilatation over all points on the surface, equals e^{2t} , but ψ is not the Teichmüller map since the dilatation is not constant. Namely, it is strictly smaller than e^{2t} for any point in the minimal component. \diamond

Step 3 (The trick): Since ψ is not the Teichmüller map, there is a Teichmüller map $\Phi: r(0) \to r(t)$ in the same homotopy class of ψ , with dilatation strictly smaller than that of ψ , which is e^{2t} . Hence the distance in moduli space from r(0) to r(t) is strictly less than $\frac{1}{2} \log e^{2t} = t$, and we are done.

3.3 ADM rays

Our goal in this subsection is to prove the following.

Theorem 3.6. A Teichmuller geodesic r(t) determined by (X_0, q_0) is ADM if and only if it is mixed Strebel.

Proof. Suppose (X_0, q_0) is mixed Strebel. Let C be a cylinder with modulus M in the homotopy class of some β . Let

$$b := \inf\{\operatorname{Ext}_{X_0}(\alpha) : \alpha \text{ is a simple closed curve}\} > 0$$

On r(t) the image of C has modulus $e^{2t}M$. By the geometric definition of extremal length, the extremal length of β on r(t) is at most e^{-2t}/M . By Kerckhoff's distance formula (Theorem 2.2 above), for any $\phi \in \text{Mod}(S)$,

$$d_{\mathrm{Teich}(S)}(\phi(r(0)), r(t)) \geq \frac{1}{2} \log \frac{Mb}{e^{-2t}} = t + \frac{1}{2} \log M + \frac{1}{2} \log b.$$

We have thus proved with $C = -\frac{1}{2} \log M - \frac{1}{2} \log b$ that mixed Strebel implies ADM.

Now assume that r(t) is ADM. We need to show that (X_0, q_0) is mixed Strebel. We argue by contradiction: assume that q_0 has no vertical cylinder.

Since r(t) is ADM, it cannot return to any compact set in $\mathcal{M}(S)$ for arbitrarily large times. Therefore, for sufficiently large t, there is a nonempty maximal collection $\beta_1(t), \ldots, \beta_n(t)$ of simple closed curves whose hyperbolic length is less than some fixed ϵ , the Margulis constant.

We divide the collection $\{\beta_i(t)\}$ into $\beta_1(t), \ldots, \beta_m(t)$, which do not belong to the vertical critical graph $\Gamma(t)$, and $\beta_{m+1}(t), \ldots, \beta_n(t)$, which do. Note that m may depend on t. For $j \leq m$, as $t \to \infty$ we have

$$\operatorname{Ext}_{r(t)}(\beta_{j}(t)) \ge |\beta_{j}(t)|_{t}^{2} \ge e^{-2t}c(t)^{2},$$
 (5)

the righthand inequality holding by Lemma 3.2, where c(t) is as given in that lemma.

Now we consider the $\beta_j(t)$ for $j \geq m+1$. Recall that $|\beta_j(t)|_t = e^{-t}|\beta_j(t)|_0$. By Theorems 4.5 and 4.6 of [Mi2], since by assumption (X_0, q_0) has no vertical cylinder, we have that for some fixed $\delta > 0$:

$$\operatorname{Ext}_{r(t)}(\beta_j(t)) \ge \frac{\delta}{-\log|\beta_j(t)|_t} = \frac{\delta}{t - \log(|\beta_j(t)|_0)},\tag{6}$$

for t sufficiently large.

By a theorem of Maskit (see [Mas]), the ratio of the hyperbolic length of $\beta_j(t)$ to its extremal length tends to 1 as $t \to \infty$. Since there are no short hyperbolic curves in the complementary regions Y to the collection $\{\beta_i(t)\}$ there is an element $\phi \in \text{Mod}(S)$ which fixes the $\beta_j(t)$ and such that $\phi(Y)$ lies in a fixed compact set of Teich(Y). We can now

apply the Minsky product theorem (see [Mi1], or the comments after Theorem 5.4 below), there exist constants C_1 , C_2 such that

$$d_{\text{Teich}(S)}(X_0, \phi(r(t))) \le \max_j \{\frac{1}{2} \log \frac{C_1}{\text{Ext}_{r(t)}(\beta_j(t))}\} + C_2$$

which by (5) and (6) is at most

$$t - \log c(t) + \log C_1 + C_2$$

for t sufficiently large. Since $c(t) \to \infty$, r(t) is not almost length minimizing. \diamond

3.4 Asymptote classes of EDM rays

We say that two rays r, r' are asymptotic if there is a choice of basepoints r(0), r'(0) so that $\lim_{t\to\infty} d(r(t), r'(t)) \to 0$. In this section we determine the asymptote classes of EDM rays. We will then use these rays in Section 4.3 to compactify $\mathcal{M}(S)$.

Definition 3.7 (Endpoint of a ray). Let (X,q) be a Strebel differential with maximal cylinders C_1, \ldots, C_p , determining a ray $r: [0,\infty) \to \text{Teich}(S)$. Cut each C_i along a circle and glue into each side of the cut an infinite cylinder. The resulting surface with punctures \hat{X} is the endpoint of r, denoted $r(\infty)$. It carries a quadratic differential $q(\infty)$ with double poles at the punctures, with equal residues, such that the vertical trajectories are closed leaves isotopic to the punctures.

The surface \hat{X} can be considered as an element of the product of moduli spaces of its connected components. We denote this moduli space, or product of moduli spaces, which we endow with the sup metric, by $\mathcal{M}(\hat{X})$.

We note that \hat{X} and $q(\infty)$ do not depend on where C_i is cut. The following definition is due to Kerckhoff [Ke].

Definition 3.8 (Modularly equivalent differentials). Suppose that (X,q), (X',q') are Strebel differentials with maximal cylinders C_1, C_2, \ldots, C_p and C'_1, \ldots, C'_r respectively. We say that these differentials are modularly equivalent if each of the following holds:

- 1. p = r.
- 2. After reindexing, every cylinder C_i is homotopic to C'_i .
- 3. There exists $\lambda > 0$ so that $Mod(C_i) = \lambda Mod(C'_i)$ for each i.

Suppose a pair of rays r, r' are modularly equivalent. Since the moduli change by a fixed factor along rays, we can choose basepoints r(0), r'(0) so that the cylinders have the same moduli at the basepoints, and define

$$d(r, r') = \lim_{t \to \infty} d_{\mathcal{M}(S)}(r(t), r'(t))$$

if the limit exists.

Theorem 3.9. With the notation as above, suppose that r and r' are modularly equivalent. Then d(r,r') exists and $d(r,r') = d_{\mathcal{M}(\hat{X})}(r(\infty),r'(\infty))$.

Assuming Theorem 3.9 for the moment, we have the following.

Corollary 3.10. Two rays r, r' are asymptotic if and only if they are modularly equivalent and they have the same endpoints $r(\infty) = r'(\infty)$.

This corollary was proven by Kerckhoff [Ke] in the case of a maximal collection of cylinders.

Proof. [of Corollary 3.10] The "if" direction follows immediately from Theorem 3.9. For the "only if" direction, we first note that the hypothesis implies that for each n sufficiently large, there is a sequence of (1 + o(1))-quasiconformal maps $f_n : r(n) \to r'(n)$. Since uniformly quasiconformal maps form a normal family (see, e.g., [Hu], Theorem 4.4.1) and r(n), r'(n) converge to $r(\infty), r'(\infty)$, there is a subsequence of $\{f_n\}$ which converges to a conformal map $f_\infty : r(\infty) \to r'(\infty)$, so that $r(\infty) = r'(\infty)$. Modular equivalence of r and r' follows immediately from (1) of Lemma 2.3 and Kerckhoff's distance formula (Theorem 2.2). \diamond

We now begin the proof of Theorem 3.9.

Proof. We first note that, exactly as in the proof of Corollary 3.10, we have

$$d_{\mathcal{M}(\hat{X})}(r(\infty), r'(\infty)) \leq \liminf_{t \to \infty} d_{\mathcal{M}(S)}(r(t), r'(t)).$$

To prove the opposite inequality we first need some preliminary lemmas.

Lemma 3.11. Suppose $\epsilon > 0$ is given. Let C_1, C_2 be Euclidean cylinders with heights R_1, R_2 and circumference 1. Now in coordinates (x, y) in the upper half-space model \mathbf{H}^2 of the hyperbolic plane, given any $n \in \mathbf{Z}$ we let $z_1 = (0, R_1)$ and $z_2 = (n, R_2)$ be points in \mathbf{H}^2 . Let

$$d_0 := d_{\mathbf{H}^2}(z_1, z_2).$$

Let p_1, q_1 marked points on the boundary of C_1 assumed to be at (0,0) and $(0,R_1)$. Let p_2, q_2 marked points on the boundary of C_2 at (0,0) and (α,R_2) in polar coordinates (θ,h) on C_2 .

Let $f(\theta)$ be an analytic function defined from the base h = 0 of C_1 to the base of C_2 such that f(0) = 0 and

$$\sup_{\theta} |f'(\theta) - 1| \le \epsilon.$$

Let γ_1 be the vertical line in C_1 joining p_1 to q_1 . Let β be the Euclidean geodesic joining (0,0) to (α, R_2) in C_2 . Let γ_2 be the local geodesic in the relative homotopy class of β twisted n times about the core curve of C_2 . Then for R_1, R_2 large enough, there is a $(1 + O(\epsilon))e^{2d_0}$ -quasiconformal map $F: C_1 \to C_2$ such that

- $F(\theta, 0) = (f(\theta), 0)$.
- $F(p_1) = p_2, F(q_1) = q_2.$
- $F(\gamma_1)$ is homotopic to γ_2 relative to the boundary of C_1 .

Proof. Define $F = (F_1, F_2)$ by

$$F(\theta, h) = ((1 - \frac{h}{R_1})f(\theta) + \frac{h(\theta + \alpha + n)}{R_1}, \frac{hR_2}{R_1});$$

the first coordinate taken modulo 1. We have $F(\theta,0) = (f(\theta),0)$ and $F(0,R_1) = (\alpha,R_2)$ and $F(\gamma_1) = \gamma_2$. We compute

$$\partial F_1/\partial \theta = \frac{h}{R_1} (1 - f'(\theta)) + f'(\theta)$$
$$\partial F_2/\partial h = \frac{R_2}{R_1}$$
$$\partial F_1/\partial h = \frac{1}{R_1} (\theta + \alpha + n - f(\theta))$$

and

$$\partial F_2/\partial \theta = 0.$$

So we have

$$|\partial F_1/\partial \theta - 1| < 2\epsilon$$

and for R_1 sufficiently large we have

$$|\partial F_1/\partial h - n/R_1| \leq \epsilon$$
.

Thus

$$|\mathrm{Jac}(F)-\left(egin{array}{cc} 1 & n/R_1 \ 0 & R_2/R_1 \end{array}
ight)|=O(\epsilon).$$

Note that the above linear map is the Teichmuller map taking the marked torus spanned by $\{(1,0),(0,R_1)\}$ to the marked torus spanned by $\{(1,0),(n,R_2)\}$. These tori correspond

to the given points in \mathbf{H}^2 and therefore the dilatation of the linear map is precisely e^{2d_0} , as claimed. \diamond

zw = t coordinates. Let S be a genus g surface with n punctures. Let C denote a collection of distinct isotopy classes of disjoint, essential, nonperipheral simple closed curves in S, and let $S \setminus C$ denote the corresponding punctured surface. The second main ingredient we are going to use are the *plumbing coordinates* introduced in [EM] that parametrize all surfaces in a neighborhood in $Z := \bigcup_{\mathcal{B}} \operatorname{Teich}(S \setminus \mathcal{B})$, where $\mathcal{B} \subseteq C$ is possibly empty, of a point in $\operatorname{Teich}(S \setminus C)$.

Suppose $\hat{X} \in \text{Teich}(S \setminus \mathcal{C})$ is a marked Riemann surface. The punctures of \hat{X} coming from cutting along \mathcal{C} appear in pairs $P_j, Q_j; j=1,\ldots,p$. Let $D_j=\{z_j: 0<|z_j|<1\}$ and $E_j=\{w_j: 0<|w_j|<1\}$ be disjoint conformal neighborhoods of P_j and Q_j , respectively. Mark points p_j, q_j on the boundary of each D_j and E_j . Let K be a compact subset of \hat{X} , with nonempty interior, and disjoint from the union of the D_j 's and the E_j 's. Let $\nu_1,\ldots,\nu_{3g-3+n-p}$ be Beltrami differentials that form a basis for the tangent space to \hat{X} in Teich $(S \setminus \mathcal{C})$ and are supported in K. Then any Riemann surface in a neighborhood of \hat{X} in Z can be described by complex coordinates

$$(s,t) = (s_1,\ldots,s_{3q-3+n-p},t_1,\ldots,t_p)$$

in a neighborhood of 0 in C^{3g-3+n} in the following way. For each small $s=(s_1,\ldots,s_{3g-3+n-p})$ we may form a Beltrami differential

$$\mu_s = \sum_{i=1}^{3g-3+n-p} s_i \nu_i$$

and find a quasiconformal map $f_s: \hat{X} \to \hat{X}_s$ with dilatation μ_s . Since the Beltrami differential $\mu_s \equiv 0$ in each D_j and E_j , the coordinates z_j, w_j serve as conformal coordinates in a neighborhood of the punctures on \hat{X}_s .

Fix a small δ . For each t_j that satisfies $0 < |t_j| < \delta$ we remove punctured discs $0 < |z_j| < |t_j|^{1/2}$ and $0 < |w_j| < |t_j|^{1/2}$ on \hat{X}_s about the paired punctures, and glue the boundary circles by

$$w_j = \frac{t_j}{z_j}$$

to give a surface X(s,t). We give a marking on X(s,t) as follows. Specify a homotopy class of arcs joining p_j and q_j crossing the glued annulus. Thus we have a marking of the surface X(s,t) consisting of the marking of \hat{X}_s , the curves along which we glued, and for each such curve, a transverse arc crossing the annulus.

We also need the following lemma.

Lemma 3.12. Let $g: \hat{X} \to \hat{X}'$ a Teichmuller map with dilatation K_0 . Given $\epsilon > 0$, there is a $(K_0 + \epsilon)$ -quasiconformal map $f: \hat{X} \to \hat{X}'$ which is conformal in a neighborhood of of the punctures.

Proof. Let μ be the dilatation of g. For any small neighborhood 0 < |z| < |t| of the punctures, let μ_t be the Beltrami differential which is 0 in 0 < |z| < |t| and μ in the complement. For some surface \hat{X}_t , there is a K_0 -quasiconformal map $f_t: \hat{X} \to \hat{X}_t$ with dilatation μ_t ; in particular f_t is conformal in 0 < |z| < |t|. As $t \to 0$, $\mu_t \to \mu$ and therefore $\lim_{t\to 0} f_t = g$ and so $\lim_{t\to 0} \hat{X}_t = \hat{X}'$. For t small enough we can find a $(1+\epsilon)$ -quasiconformal map $h_t: \hat{X}_t \to \hat{X}'$ which is conformal in a neighborhood of the punctures by the discussion of the (s,t) coordinates. Our desired map is $f = h_t \circ f_t$. \diamond

Now we begin the proof of the bound

$$\limsup_{t \to \infty} d_{\mathcal{M}(S)}(r(t), r'(t)) \le d_{\mathcal{M}(\hat{X})}(r(\infty), r'(\infty)).$$

Let $p_i, q_i, i = 1, ..., p$ be the paired punctures on $r(\infty)$, and let z_i be the coordinate at p_i so that for some $a_i > 0$,

$$q(\infty)=rac{a_i^2}{z_i^2}dz_i^2,$$

we have a similar coordinate in a neighborhood of q_i . Let ζ_i the corresponding coordinate for $q'(\infty)$ on $r'(\infty)$ in a neighborhood of p'_i so that

$$q'(\infty) = \frac{b_i^2}{\zeta_i^2} d\zeta_i^2.$$

Circles in these coordinates are vertical leaves for $q(\infty)$ and $q'(\infty)$ and have lengths $2\pi a_i$ and $2\pi b_i$ respectively. We recover the surfaces along r(t) by removing punctured discs of radius $\delta_i^{1/2}(t)$ around p_i and q_i and glueing the resulting surfaces along their boundary. We have a similar picture for r' with corresponding $\delta_i'^{1/2}(t)$. The assumption that r, r' are modularly equivalent means that for each δ_i there is δ_i' , such that the resulting cylinders A_i, A_i' on r(t), r'(t) have the same modulus. For convenience we drop the subscript i.

Let $K = e^{d_{\mathcal{M}(\hat{X})}(r(\infty),r'(\infty))}$. Let $F_2 : r'(\infty) \to r(\infty)$ be the $(K + \epsilon)$ -quasiconformal map given by Lemma 3.12 that is conformal in a neighborhood of all of the punctures. Here $\epsilon > 0$. We may take a fixed κ' so that F_2 is conformal inside the circle of radius κ' inside each punctured disc. This means that we can take ζ as a conformal coordinate in a neighborhood of the puncture on $r(\infty)$ and so the map F_2 is the identity on the circle $|\zeta| = \kappa'$ in these coordinates.

Consider the annulus $B' \subset A'$ defined by

$$B' = \{ \zeta : |\delta'^{1/2}| < |\zeta| < \kappa' \}.$$

Consider also the annulus $B \subset r(\infty)$ which in the z plane is bounded by the circle of radius $|\delta^{1/2}|$ and the curve ω which is the image under F_2 of the circle of radius κ' . In the ζ coordinates on $r(\infty)$, B is bounded by the circle $|\zeta| = \kappa'$ and an analytic curve γ which is the image under the holomorphic change of coordinate map $\zeta = \zeta(z)$ of the circle of radius $|\delta^{1/2}|$.

Since κ' is fixed, we have

$$\lim_{\delta' \to 0} \frac{\operatorname{Mod}(B')}{\operatorname{Mod}(A')} = 1$$

and since ω is fixed,

$$\lim_{\delta \to 0} \frac{\operatorname{Mod}(B)}{\operatorname{Mod}(A)} = 1.$$

Since Mod(A) = Mod(A') we therefore have

$$\lim_{\delta \to 0} \frac{\operatorname{Mod}(B')}{\operatorname{Mod}(B)} \to 1. \tag{7}$$

For small enough δ we wish to find a $(1 + O(\epsilon))$ quasiconformal map F_1 from B' to B such that

- for $\zeta = \delta'^{1/2} e^{i\theta}, z = F_1(\zeta) = \delta^{1/2} e^{i\theta}$
- for $|\zeta| = \kappa'$, $F_1(\zeta) = \zeta$.

In other words, the desired F_1 is the identity on the circle of radius κ' and takes the circle of radius $\delta'^{1/2}$ in the ζ coordinates to the circle of radius $\delta^{1/2}$ in the z coordinates. We also find a corresponding map F_1 for neighborhoods of q_i, q_i' . We then will glue these maps F_1 along the circle of radius $\delta'^{1/2}$ together to give a $1+O(\epsilon)$ map, again denoted F_1 , on the glued annulus to the annulus found by gluing along the circle of radius $\delta^{1/2}$ in the z coordinates. We then glue F_1 to F_2 along the circles of radius κ' to give a $(K + O(\epsilon))$ -quasiconformal map from r'(t) to r(t).

We now find the map F_1 . By (7) for all sufficiently small δ ,

$$|\frac{\operatorname{Mod}(B')}{\operatorname{Mod}(B)} - 1| \le \epsilon/2$$

Find a conformal map $h_{\delta}(z)$ from B to a round annulus

$$B_1 = \{w : \delta''^{1/2} < |w| < \kappa'\}$$

with the normalization that $h_{\delta}(\kappa') = \kappa'$. The composition

$$\delta'^{1/2}e^{i\theta} \to \delta^{1/2}e^{i\theta} \to h_{\delta}(z)$$

is a map $w = f_{\delta}(\zeta)$ from the circle of radius $\delta'^{1/2}$ in the ζ plane to the circle of radius $\delta''^{1/2}$ in the w plane. Similarly we have a map $w = g_{\delta}(\zeta)$ from the circle of radius κ' in the ζ -plane to the circle of radius κ' in the w-plane.

We wish to show that, as $\delta \to 0$, we have $|f'_{\delta} - (\delta''/\delta')^{1/2}| \to 0$ and $|g'_{\delta} - 1| \to 0$. In that case after mapping the annuli B_1, B' to flat cylinders with base 0 and heights R_1, R_2 respectively, by a logarithm map, the induced maps on the top and bottom of the cylinders have derivatives almost constantly 1. We then can apply Lemma 3.11 with $R_1/R_2 \to 1$ and n = 0.

Considering B as an annulus in the ζ coordinates, with outer boundary the fixed circle $|\zeta| = \kappa'$, as $\delta \to 0$, the conformal maps h_{δ} converge to a conformal self map of the punctured disc $0 < |\zeta| < \kappa'$. It extends to a conformal map taking 0 to 0. The only such conformal maps are rotations. But by our normalization of the h_{δ} 's, that map must be the identity. Thus as $\delta \to 0$, the maps h_{δ} converge uniformly to the identity, and therefore g'_{δ} converges uniformly to 1 on the circle of radius κ' .

By replacing z with $z/\delta^{1/2}$, and w with $w/\delta''^{1/2}$ we also can consider h_{δ} as a map from the annulus B in the z plane with inner boundary the unit circle, to B_1 , another annulus with inner boundary the unit circle. As $\delta \to 0$, h_{δ} converges to a conformal map of the exterior of the unit disc to the exterior of the unit disc, taking ∞ to ∞ . The limiting conformal map is therefore again the identity. Thus the map h_{δ} from the circle of radius $\delta^{1/2}$ to the circle of radius $\delta''^{1/2}$ in the w plane has derivative approaching $(\delta''/\delta)^{1/2}$ as $\delta \to 0$. Since the map from the circle of radius $\delta'^{1/2}$ in the ζ plane to the circle of radius $\delta^{1/2}$ in the z plane has derivative $(\delta/\delta')^{1/2}$, applying the chain rule the composition f_{δ} has derivative converging to $(\delta''/\delta')^{1/2}$ as $\delta \to 0$. We are now in a position to apply Lemma 3.11. This completes the proof. \diamond

4 The iterated EDM ray space and the Deligne-Mumford compactification

In this section we introduce a functor $X \mapsto \overline{X}^{ir}$ defined on a certain collection of metric spaces X. The space \overline{X}^{ir} will be constructed via certain equivalence classes of EDM rays, and will have the structure of a metric stratified space (see below). We will then prove that this functor applied to $\mathcal{M}(S)$ produces the Deligne-Mumford compactification $\overline{\mathcal{M}(S)}^{\mathrm{DM}}$; that is, we will find a stratification-preserving homeomorphism from $\overline{\mathcal{M}(S)}^{ir}$ to the Delgine-Mumford compactification $\overline{\mathcal{M}(S)}^{\mathrm{DM}}$ which is an isometry on each stratum.

4.1 The iterated EDM ray space

A metric space Y is said to have the *local unique extension property* if for every $y \in Y$ there is a neighborhood U of y with the property that any two points in U can be connected by a unique geodesic, and further, that such geodesic has a unique extension in U.

This is a property that holds for each moduli space. Now spaces that appear on the boundary of the Deligne-Mumford compactification are naturally products of moduli spaces. We wish to consider metric spaces somewhat more abstractly. In the Appendix we will prove the following.

Theorem 4.1 (Uniqueness of product decomposition). Suppose $Z = Y_1 \times Y_2$, where Z is endowed with the sup metric, and where Y_1, Y_2 are connected metric spaces, each of which satisfies the unique local extension property. Then given any other way of writing $Z = X_1 \times \cdots \times X_m$ with the sup metric, it must be that m = 2 and, after perhaps switching factors, $X_i = Y_i$ for i = 1, 2.

Now suppose (X, d) can be written as $X_1 \times \ldots X_m$. (possibly with m = 1). We will consider rays in each factor.

Definition 4.2 (Isolated rays). We say that a ray r is isolated if the following two properties hold

- 1. there is a factor X_j such that $r \subset X_j$ and r is an EDM ray in X_j .
- 2. for every $p \in X_j$, the set of asymptote classes of EDM rays $[r'] \subset X_j$ which are a bounded distance from r, and which have some representative passing through p, is countable.

We will now define a space \overline{X}^{ir} inductively, building it inductively, stratum by stratum. The level k stratum will be denoted $D_k(X)$.

Henceforth every metric space (Y, d) that appears as a factor in a product will be assumed to have the following three properties:

Standing Assumption I (Limits exist): For any two isolated EDM rays r_1, r_2 in Y that are a bounded distance apart, there are initial points $r_1(0), r_2(0)$ such that $\lim_{t\to\infty} d(r_1(t), r_2(t))$ exists and is a minimum among all choices of basepoints.

Standing Assumption II (Asymptotes are uniformly asymptotic): For any $\epsilon > 0$, any asymptote class of isolated EDM rays [r], any representative r of [r], and any choice of basepoint r(0), there is a $T = T(r, r(0), \epsilon)$ such that for any such asymptotic pairs r, r' the rays $r([T, \infty))$ and $r'([T', \infty))$ are within Hausdorff distance ϵ of each other.

If a metric space X contains isolated rays, we consider the set Asy(X) of all asymptote classes of isolated EDM rays [r] in X. With Standing Assumption I in hand, we can endow Asy(X) with a distance function via $d_{asy}([r_1], [r_2]) = \lim_{t\to\infty} d(r_1(t), r_2(t))$ for choice of basepoints that minimizes this limit. It is easy to check that this defines a metric.

Standing Assumption III: Asy(X) cannot be written as a product in the sup metric of 3 or more factors.

Note then that it follows immediately from Theorem 4.1 that Asy(X) can be written uniquely as a product. We note that, when constructing one metric space from another, the standing assumptions must be proved each time.

Let $(D_0(X), d_0) := (X, d)$. We assume $D_0(X)$ is not a product.

Step 1 (Inductive step): Suppose we are given the metric space $D_k(X)$, written as a product of factors $X_1 \times \ldots \times X_m$ with the metric $d_k(\cdot, \cdot)$, where d_k is the sup of the metrics d^j of the factors. If none of the factors X_j contains isolated EDM rays, define $D_m(X) = \emptyset$ for all m > k and stop the inductive process. If some factor X_j contains isolated rays then we set

$$D_{k+1}^{j}(X) = X_1 \times \ldots \times X_{j-1} \times \operatorname{Asy}(X_j) \times X_{j+1} \times \ldots \times X_m.$$

We can endow $D_{k+1}^j(X)$ with a distance function d_{k+1}^j as the sup metric on the factors. From the comment after Standing Assumption III we note that if $Asy(X_j)$ is a product, then it can be written uniquely as a product. Thus, given the product representation of $D_k(X)$, we have a unique product representation of $D_{k+1}^j(X)$.

Note also that if two points in $D_{k+1}^j(X)$ have an infinite distance from each other, then they are in different components of $D_{k+1}^j(X)$. We then set

$$D_{k+1}(X) = \sqcup_{j=1}^{m} D_{k+1}^{j}(X)$$

with metric d_{k+1} which is the corresponding metric d_{k+1}^j on each term in the disjoint union.

Step 2 (Topology): We will inductively define a topology on the disjoint union $Y := \bigcup_{j=0}^{\infty} D_j(X)$, as follows.

Using Standing Assumption II, for every $[r_0] \in \operatorname{Asy}(X_j)$ and every $\epsilon > 0$ we can define an ϵ -neighborhood $V_{\epsilon}([r_0])$ of $[r_0]$ in $\operatorname{Asy}(X_j) \cup X_j$. Consider the set of equivalence classes of isolated rays $[r] \in \operatorname{Asy}(X_j)$ such that $d^j([r], [r_0]) < \epsilon$ and set $V^j_{\epsilon}([r_0])$ to be the union of the set of such rays and the following set. For each such ray [r] and each $r \in [r]$ include in $V^j_{\epsilon}([r_0])$ the set $\{r(t) : t \geq T(r, r(0), \epsilon)\}$.

We are now ready to define the topology.

Definition 4.3. Let $j \geq 0$. Suppose $\vec{x}(n)$ is a sequence in $D_k(X)$ and $(\vec{x}, [r]) \in D^j_{k+1}(X)$. We say $\vec{x}(n) \to (\vec{x}, [r])$ if there exists $t_n \to \infty$ such that

- 1. for $i \neq j$, $\lim_{n \to \infty} d^i(x_i(n), x_i) = 0$
- 2. $\lim_{n\to\infty} d^j(x_j(n), r(t_n)) = 0$ for some representative r of [r].

Now suppose inductively for each k, m, and for each sequence $\vec{x}(n) \in D_k(X)$, and $y \in D_{k+m}(X)$ we have defined what it means for $\vec{x}(n)$ to converge to y.

Definition 4.4. Suppose $\vec{x}(n) \in D_k(X)$ and $z \in D_{k+m+1}(X)$. We say $\vec{x}(n) \to z$ if there exists j, points $(\vec{x'}(n), [r_n]) \in D^j_{k+1}(X)$, a sequence $\epsilon_n \to 0$, representatives r_n and times t_n such that

- 1. $\lim_{n\to\infty} d^i(x_i(n), x'_i(n)) = 0 \text{ for } i \neq j.$
- 2. $\lim_{n\to\infty} d^j(x_j(n), r_n(t_n)) = 0.$
- 3. $r_n(t_n) \in V_{\epsilon_n}([r_n])$.
- 4. $\lim_{n\to\infty} (\vec{x'}(n), [r_n]) = z$.

The first condition just says that one has convergence in the factors where one is not considering isolated rays. Notice the last condition inductively makes sense since $(\vec{x'}(n), [r_n]) \in D_{k+1}(X)$ and $z \in D_{k+m+1}(X)$ and k+m+1-(k+1)=m.

We thus obtain a topological space which is stratified by $\{D_k(X)\}$, and in fact each stratum is a metric space (by Standing Assumption I). Note that X is open and dense in Y. We are actually interested in a somewhat simpler space, obtained as a certain quotient of Y, as follows.

Step 3 (Identifications): The space Y provides a natural "boundary" for X, although the construction may give multiple copies of the same boundary component. To remedy this, we will identify points that "should" be distance zero from each other. In some sense this is like Cauchy's scheme for completing metric spaces.

We make no identifications of points in $D_0(X)$. Now suppose inductively we have made identifications of points in $D_j(X)$ for all $j \leq k$ and $P, Q \in D_{k+1}(X)$.

Definition 4.5. We say $P \sim Q$ if there exist sequences x_n, y_n in the same component of $D_{k-1}(X)$ such that

- 1. $\lim_{n\to\infty} x_n = P$ and $\lim_{n\to\infty} y_n = Q$.
- 2. $\lim_{n\to\infty} d_{k-1}(x_n, y_n) = 0$.

This is clearly an equivalence relation. We denote the quotient space of Y by this equivalence relation by \overline{X}^{ir} , and call it the *iterated EDM ray space* associated to X. This is evidently a functor from metric spaces (satisfying the standing assumptions) and isometries to metric spaces and isometries. If Y turns out to be a compactification of X, then since we only identified certain points in $Y \setminus X$, it follows that \overline{X}^{ir} is also a compactification of X.

Example 4.6. For X the upper quadrant in $\mathbf{R}^2 = \mathbf{R}^+ \times \mathbf{R}^+$ with the sup metric, D_1 has two components, each of which is an infinite ray. A point in one component corresponds to a vertical ray, with the distance function equal to the distance function between vertical rays, i.e. the difference of their x coordinates. The points in the other component correspond to horizontal rays, with the distance being the difference of their y coordinates. Since D_1 is a disjoint union of two rays, D_2 consists of two points. The sequence (n,n) converges to each of the two points in D_2 , and so these points are identified. Thus in this case \overline{X}^{ir} is a closed square.

4.2 Metric stratified spaces

We would like to keep track of structures finer than topological type. To do so we will need the following standard concept.

Definition 4.7. A stratification of a second countable, locally compact Hausdorff space X is a locally finite partition S_X into open subsets S satisfying:

- 1. Each element $S \in \mathcal{S}_X$, called a stratum, is a connected topological space in the induced topology.
- 2. For any two strata $S_1, S_2 \in \mathcal{S}_X$, if $\overline{S_1} \cap S_2 \neq \emptyset$ then $\overline{S_1} \supset S_2$.

A space X with a stratification, with each stratum endowed with the structure of a metric space, is called a metric stratified space.

Inclusion $\overline{S_1} \supset S_2$ defines a partial ordering $S_1 > S_2$ on the elements of S_X . The depth, or level of a stratum T is the maximal n so that there is a chain

$$S_0 > \cdots > S_n = T$$

with $S_i \in \mathcal{S}_X$. Note that since \mathcal{S}_X is locally finite, any such chain is finite, although a priori one might have strata of infinite depth.

Example 4.8. The iterated EDM ray space \overline{X}^{ir} of §4.1 has a natural stratification, where the level k strata are the components of $D_k(X)$.

4.3 The Deligne-Mumford compactification

Deligne-Mumford [DM] constructed a compactification $\overline{\mathcal{M}(S)}^{DM}$ of $\mathcal{M}(S)$, called the *Deligne-Mumford compactification*, which they proved is a projective variety. As such, $\overline{\mathcal{M}(S)}^{DM}$ is endowed with the structure of a stratified space. Bers [Be] also gave a construction of $\overline{\mathcal{M}(S)}^{DM}$ as a stratified space. Points of the level k strata of $\overline{\mathcal{M}(S)}^{DM}$ are given by conformal structures on k-noded Riemann surfaces; the set of strata are parametrized by the set of combinatorial types of collections of nodes (see [Be, DM]).

The topology on $\overline{\mathcal{M}(S)}^{\mathrm{DM}}$ is as follows. On each stratum the topology is just that of the corresponding moduli space. Points X_n converge to some Y in a lower level stratum if for every neighborhood N of the union of nodes in Y, there is a conformal map $(Y \setminus N) \to X_n$ for n sufficiently large. We endow each stratum of $\overline{\mathcal{M}(S)}^{\mathrm{DM}}$ with the corresponding Teichmüller metric, thus giving $\overline{\mathcal{M}(S)}^{\mathrm{DM}}$ the structure of a metric stratified space.

Our goal in this section is to reconstruct $\overline{\mathcal{M}(S)}^{\mathrm{DM}}$ as a metric stratified space (but not as a projective variety) as the iterated EDM ray space $\overline{\mathcal{M}(S)}^{ir}$ associated to $\mathcal{M}(S)$. We therefore begin by applying the construction from the previous subsection to $\mathcal{M}(S)$, endowed with the Teichmüller metric. We note first that each moduli space $\mathcal{M}(S)$ stissies the local unique extension property.

We characterize the isolated rays in $\mathcal{M}(S)$, and identify the metric they give on the stratum $D_1(\mathcal{M}(S))$.

Proposition 4.9. Let S be a surface of finite type. Then a ray in $\mathcal{M}(S)$ is an isolated EDM ray if and only if it is a one-cylinder Strebel ray. Let r and r' be one-cylinder Strebel rays. Suppose the cylinders of r and r' both have core curves of the same topological type as a fixed simple closed curve γ . Then $d_1(r,r')$ in $D_1(\mathcal{M}(S))$ exists, and coincides with the Teichmüller distance between $r(\infty)$ and $r'(\infty)$ in the boundary moduli space $\mathcal{M}(S \setminus \gamma)$.

We remark that if the cylinder defining the Strebel ray is given by a separating curve, then S' is disconnected, and so $\mathcal{M}(S \setminus \gamma)$ is itself a product of smaller moduli spaces.

Proof. By Theorem 1.4, a ray in $\mathcal{M}(S)$ is EDM if and only if it is Strebel. By Theorem 21.7 of [St], on each Riemann surface there is a unique one-cylinder Strebel differential in each homotopy class of simple closed curve. There are only countably many such homotopy classes. Moreover, given a collection of more than one distinct homotopy class of disjoint curves, the set of Strebel differentials with cylinders in those homotopy classes is uncountable (again, by Theorem 21.7 of [St]). Moreover by Theorem 2 of [Ma], any two Strebel differentials with homotopic cylinders are a bounded distance apart. However (again by Theorem 21.7 of [St]) they are not modularly equivalent and so these classes are not isolated. It follows easily from Lemma 2.3 that each of these is an unbounded distance from

a ray defined by a one-cylinder Strebel differential. These facts together imply that the isolated rays coincide with the one-cylinder Strebel rays.

The fact that the set of asymptote classes of one-cylinder Strebel rays on any moduli space is homeomorphic to the moduli spaces of one smaller complexity, and that the distance between one cylinder Strebel rays of the same type exists and is equal to the Teichmuller distance on the correpsonding one complexity smaller moduli space, is the content of Theorem 3.9. The fact that isoated EDM rays determined by combinatorially equivalent curves are not bounded distance apart follows from Lemma 2.3. \diamond

With the setup above, we can now prove the main result of this section: that $\overline{\mathcal{M}(S)}^{ir}$ and $\overline{\mathcal{M}(S)}^{\mathrm{DM}}$ are isomorphic as metric stratified spaces.

Theorem 4.10. The iterated EDM ray space $\overline{\mathcal{M}(S)}^{ir}$ associated to $\mathcal{M}(S)$ is homeomorphic to the Deligne-Mumford compactification $\overline{\mathcal{M}(S)}^{\mathrm{DM}}$ via a stratification-preserving homeomorphism which is an isometry on each stratum.

Proof. First recall that the set of level k strata of $\overline{\mathcal{M}(S)}^{DM}$ is parametrized by the set of combinatorial types of k-tuples of simple closed curves on S, representing the curves that are pinched to nodes. Each level k stratum corresponding to a k-tuple $\{\alpha_1, \ldots, \alpha_k\}$ is a product of the moduli spaces of the punctured surfaces consisting of the components of $S \setminus \{\alpha_1, \ldots, \alpha_k\}$. Further, we have endowed each stratum with the Teichmüller metric of the corresponding moduli space or, in the case of disconnected surfaces, with the sup metric on the product of moduli spaces.

Step 1 (Defining a surjective map): We first define a map $\psi: \bigcup_{k=0}^{\infty} D_k(\mathcal{M}(S)) \to \overline{\mathcal{M}(S)}^{\mathrm{DM}}$ inductively, as follows. On $D_0(\mathcal{M}(S))$ we simply let ψ be the identity map. By Proposition 4.9, the isolated EDM rays in $D_0(\mathcal{M}(S))$ are precisely the one-cylinder Strebel rays. The equivalence classes of one-cylinder Strebel differentials correspond precisely to the topological types of simple closed curves on S. By Corollary 3.10, the asymptote classes of one-cylinder Strebel rays r correspond to the possible endpoints $r(\infty)$. By Strebel's existence theorem (Theorem 23.5 of [St])), every possible endpoint can occur, so that $D_1(\mathcal{M}(S))$ consists of all possible surfaces obtainable by pinching a single simple closed curve on S. Thus $D_1(\mathcal{M}(S))$ is the disjoint union of moduli spaces, one for each topological type of simple closed curve. By Theorem 3.9, the metric d_1 on D_1 coincides with the corresponding Teichmüller metric on each component of $D_1(\mathcal{M}(S))$. We define ψ on each component of $D_1(\mathcal{M}(S))$. If the component is not a product we map an asymptote class [r] of rays to the corresponding endpoint $r(\infty)$. If the component is a product, then for each factor we define ψ by fixing the coordinates of the other factors and map an asymptote class of rays in the factor to its endpoint. By the above, on each component, this map is an isometry onto

the component of $\overline{\mathcal{M}(S)}^{DM}$ corresponding to the appropriate combinatorial type of simple closed curve.

Suppose now that we have proven that each component of $D_k(\mathcal{M}(S))$ is isometric via a map ψ to a (products of) moduli spaces, and the map is onto the collection of moduli spaces, one for each combinatorial type of k-tuple of simple closed curves. Fix any component of $D_k(\mathcal{M}(S))$, corresponding to a k-tuple $\{\alpha_1,\ldots,\alpha_k\}$, and let $\mathcal{M}(S')$ be the corresponding (products of) moduli spaces $\mathcal{M}(S_1)\times\ldots\times\mathcal{M}(S_p)$, where $S'=S\setminus\{\alpha_1,\ldots,\alpha_k\}$. For each factor in this product we find the asymptote classes of isolated EDM rays, again given by the one cylinder Strebel differentials. We thus obtain components of $D_{k+1}(\mathcal{M}(S))$, and these components correspond to the possible combinatorial types of (k+1)-tuples obtainable from α_1,\ldots,α_k by adding a single simple closed curve. We again define ψ on each component by sending each asymptote class [r] to $r(\infty)$, and if the component is a product, defining it to be the identity on the other coordinates. As above, we see that ψ is an isometry when restricted to any of the fixed components just obtained. By Strebel's theorem again, the map is onto all $(k+1)^{\text{st}}$ strata in $\overline{\mathcal{M}(S)}^{\text{DM}}$.

We have therefore inductively defined a map

$$\psi: \bigcup_k D_k(\mathcal{M}(S)) \to \overline{\mathcal{M}(S)}^{\mathrm{DM}}$$

which we have shown to be onto (by Strebel's existence theorem), and which is an isometry when restricted to any fixed component of any fixed $D_k(\mathcal{M}(S))$.

Step 2 (The standing assumptions hold): Standing Assumption I holds by the fact discussed above, that if two EDM rays are defined by pinching the same combinatorial type of curve then the rays have an asymptotic distance apart, and by the fact that if the topological tyes are different then the rays are not bounded distance apart. The latter follows from Lemma 2.3

Now we show Standing Assumption II holds. Let [r] be an asymptotic class of isolated EDM ray on any moduli space with r any representative. As we have seen, on the surface $r(\infty)$ there is a quadratic differential $q(\infty)$ with double poles at the paired punctures, such that the vertical trajectories are all closed curves of equal length isotopic to the punctures. Since $q(\infty)$ is the unique (up to scalar multiple) quadratic differential with this property, any two representatives determine the same $q(\infty)$. Since the Strebel differentials along r can be reconstructed by cutting out punctured discs on $r(\infty)$ and gluing along the boundary circles of $q(\infty)$, the ray r is determined by a single twist parameter; namely, how the circles are glued to each other. Thus the Strebel differentials on any two rays differ by only a twist about the core curve, and the amount of twisting is bounded by the length of the curve. For any two points $r_1(t_1)$ and $r_2(t_2)$ along two such rays, if the moduli of the cylinders M_1, M_2

are equal and large, then $d(r(t_1), r_2(t_2))$ is small; there is a $O(1 + 1/M_1)$ -quasiconformal map of the cylinders that realizes the twisting. Standing Assumption II follows.

Standing Assumption III holds since for each factor the corresponding space of isolated EDM rays is a product of at most two factors. There are two factors if and only if the pinching curve is separating on that surface.

Step 3 (ψ is continuous): Suppose $x_n \in D_k(\mathcal{M}(S))$ converges to $z \in D_{k+m}(\mathcal{M}(S))$ as in Definitions 4.3 or 4.4. The proof of continuity of ψ is by induction on m. Assume m=1. If the component of D_k containing x_n is a product, then by definition all of the coordinates but one of $\psi(x_n)$ in the product coincide with the corresponding coordinates of x_n . By assumption, these converge to the corresponding coordinates of $\psi(z)$. Thus we can assume that the component of D_k is not a (nontrivial) product. Then $\psi(z)$ is the Riemann surface $r(\infty)$, where r is an EDM ray in $D_k(\mathcal{M}(S))$, and $d_k(x_n, r(t_n)) \to 0$ for a sequence $t_n \to \infty$. The fact that $r(\infty)$ is the endpoint of r says that $\psi(r(t_n)) \to \psi(z)$ as $t_n \to \infty$ in the topology of $\overline{\mathcal{M}(S)}^{\mathrm{DM}}$. The fact that $d_k(x_n, r(t_n)) \to 0$ says there is a sequence of (1 + o(1))-quasiconformal maps of $\psi(x_n)$ to $\psi(r(t_n))$. These converge to a conformal map of a limit $\psi(r(t_n))$ to $\psi(z)$. Thus any such limit must in fact coincide with $\psi(z)$.

Now suppose the continuity of ψ has been proved for all $p \leq m$ and m = p + 1. Again it suffices to assume that D_k is not a product. Let y_n a sequence in $D_{k+1}(\mathcal{M}(S))$ such that $y_n \to z$ as in Definition 4.4. There is a sequence of isolated rays r_n in D_k defined by one-cylinder Strebel differentials with core curve some γ such that $y_n = r_n(\infty)$. By the induction hypothesis $\psi(y_n) \to \psi(z)$. Now assumption (2) in the definition of the topology implies that

$$\operatorname{Ext}_{r_n(t_n)}(\gamma) \to 0,$$

for otherwise there would be rays in the same asymptote class whose distance from $r_n(t_n)$ does not tend to 0. Form the (s,t) coordinate neighborhood about $\psi(z)$ corresponding to the curves of $\psi(y_n)$ that are pinched. Since $\psi(y_n) \to \psi(z)$, we have that $\psi(y_n)$ lies in this neighborhood for large n. We can assume that the coordinates $t_2, \ldots, t_k \to 0$ as $\psi(y_n) \to \psi(z)$. By reindexing we can assume that pinching γ corresponds to plumbing along the t_1 coordinate. The statement about extremal lengths implies that the t_1 coordinate of $\psi(r_n(t_n))$ tends to 0 as $n \to \infty$. Now just as in the proof of Theorem 3.9 we have $\psi(r(t_n)) \to \psi(z)$. By assumption, there is a sequence of (1 + o(1))-quasiconformal maps from $\psi(x_n)$ to $\psi(r(t_n))$, and therefore $\psi(x_n) \to \psi(z)$ as well. This shows that ψ is continuous.

Step 4 (Factoring ψ): Now the map ψ itself is not injective, since one can have two combinatorially distinct j-tuples of curves which become combinatorially equivalent when one additional curve is added. For example, if S is closed of genus 2, then in $D_2(\mathcal{M}(S))$ the component corresponding to pinching a separating and nonseparating curve is counted

twice. However we show now that the final identification Step 4 precisely identifies, by definition, such tuples. Namely we show that the map ψ factors through a map

$$\Psi: \overline{\mathcal{M}(S)}^{ir} \to \overline{\mathcal{M}(S)}^{\mathrm{DM}}$$
.

Suppose $z, z' \in D_{k+1}(\mathcal{M}(S))$ and $z \sim z'$. We have to show $\psi(z) = \psi(z')$. By definition there are sequences $x_n, x'_n \in D_{k-1}(\mathcal{M}(S))$ that satisfy $d_{k-1}(x_n, x'_n) \to 0$; $x_n \to z$, $x'_n \to z'$. By the continuity of ψ we have $\psi(x_n) \to \psi(z)$ and $\psi(x'_n) \to \psi(z')$. Since $d_{k-1}(x_n, x'_n) \to 0$, there is a sequence of (1 + o(1))-quasiconformal maps from $\psi(x_n)$ to $\psi(x'_n)$. Therefore we also have $\psi(x'_n) \to \psi(z)$ and so $\psi(z) = \psi(z')$. We have shown that there is a well-defined map $\Psi: \overline{\mathcal{M}(S)}^{ir} \to \overline{\mathcal{M}(S)}^{DM}$.

Step 5 (Ψ is injective): We must prove that if $\Psi(z) = \Psi(z')$, then z has been identified with z'. We can assume z, z' are in different components of $D_{k+1}(\mathcal{M}(S))$. Again we can assume the components are not products; hence they are endpoints of rays r, r' in different components E, E' of $D_k(\mathcal{M}(S))$. Let $x_n \in D_{k-1}(\mathcal{M}(S))$ such that $x_n \to z$. We wish to show $x_n \to z'$ as well, for then z is identified with z'. We have $X_n := \Psi(x_n) \to Z := \Psi(z)$. We form a (s,t) coordinate neighborhood system about Z = Z'. Since Z lies in a moduli space of two fewer dimensions than X_n , there are two plumbing coordinates t_1, t_2 such that the coordinates $t_1(n), t_2(n)$ of X_n are both nonzero.

We can assume that points of E' have coordinate $t_1 = 0$ and the t_2 coordinate tends to 0 along the ray r'(u) as $u \to \infty$. For each n, we can find a time u_n such that the modulus of the cylinder on $\Psi(r'(u_n))$ coincides with the modulus of the annulus on X_n corresponding to the plumbing in the t_2 coordinate. For each such $r'(u_n)$ there is a ray $r'_n \subset D_{k-1}(\mathcal{M}(S))$ such that $r'(u_n) = r'_n(\infty)$. We can choose a time s_n so that the corresponding cylinder on $r'_n(s_n)$ has the same modulus as the annulus on X_n corresponding to plumbing in the t_1 coordinate. Now just as in the proof of Theorem 3.9, as $n \to \infty$ there is a sequence of (1 + o(1))-quasiconformal maps from X_n to $\Psi(r'(s_n))$ and by the definition of the topology on the union of the $D_j(\mathcal{M}(S))$ we have that $x_n \to z'$.

Step 6 (Ψ^{-1} is continuous): Suppose then that $X_n \in \mathcal{M}(S')$ converges to Z in $\overline{\mathcal{M}(S)}^{\mathrm{DM}}$. Again we can form an (s,t) coordinate neighborhood system about Z such that, after reindexing, the t coordinates of X_n are given by $(t_1(n),\ldots,t_k(n)) \neq 0$. Here k is the number of curves of X_n that we pinch to get Z. The proof is by induction on k and resembles the proof that Ψ is injective. Suppose k=1. Let r be the Strebel ray with endpoint $r(\infty)=Z$, so by definition, $\Psi([r])=Z$. For each n, we can find a time u_n such that the modulus of the cylinder on $r(u_n)$ is the same as the modulus about the pinching curve on X_n found by the plumbing construction. Now again just as in the proof of Theorem 3.9, for any ϵ , for n large enough, we can find a $(1+\epsilon)$ -quasiconformal map from X_n to $r(u_n)$. Then by definition, $X_n \to [r] = \Psi^{-1}(Z)$ in the topology of $\overline{\mathcal{M}(S)}^{ir}$.

Now for the induction step. Suppose we have proven the desired limit for k-1, where Z is found by pinching along k curves. We have $Z=\Psi([r_0])$ for some ray r_0 . Let Y_n have the same (s,t) coordinates as X_n except that we require $t_1=0$. This means that we find Z from Y_n by pinching k-1 curves. Let q_n be the Strebel differential on Y_n with double poles at the punctures corresponding to $t_1=0$, and let r_n be the corresponding Strebel ray with endpoint $r_n(\infty)=Y_n$. By definition, $\Psi([r_n])=Y_n$. Now $Y_n\to Z$ in $\overline{\mathcal{M}(S)}^{\mathrm{DM}}$, and by the induction hypothesis on the continuity of the map Ψ^{-1} , we see that $[r_n]\to [r_0]$. Just as above we may choose u_n so that the modulus of the cylinder on $r_n(u_n)$ is the same as the modulus of the annulus corresponding to the t_1 coordinate in the plumbing construction. By definition of the topology of $\overline{\mathcal{M}(S)}^{ir}$ it is again enough to prove that $d_{\mathcal{M}(S)}(X_n, r_n(t_n)) \to 0$. But this again follows just as in the proof of Theorem 3.9: there is a conformal map $X_n \to \Psi(r(u_n))$ in the complement of annuli with large but equal moduli; then for any ϵ , for n large enough, we can find a $(1+\epsilon)$ -quasiconformal map from X_n to $\Psi(r(u_n))$. This completes the proof.

5 Further geometric properties

5.1 A strange example

In this subsection we indicate some of the difficulties of the Teichmüller geometry of $\mathcal{M}(S)$ by exhibiting two sequences of EDM rays r_n, r'_n , with the following properties: there exists a constant D > 0 and sequences of times $t_n, t'_n \to \infty$ such that $d_{\mathcal{M}(S)}(r_n(t_n), r'_n(t'_n)) \leq D$, each sequence r_n, r'_n converges to an EDM ray r_∞, r'_∞ uniformly on compact intervals of time, and yet r_∞ does not stay within a bounded distance of r'_∞ . This example violates Assumption 9.11 of [JM], so that the Ji-MacPherson compactification method cannot be applied to $\mathcal{M}(S)$. This partially explains why we took a different approach.

We construct a sequence of rays r_n as follows. Let r_0 be a Strebel ray corresponding to a maximal collection of curves $\beta_1, \ldots, \beta_{3g-3+n}$ whose cylinders have equal moduli. Note that $r_0(\infty)$ is the unique maximally noded Riemann surface within its combinatorial equivalence class. Let α be a curve distinct from the β_i and therefore it has positive intersection with some β_j . Let T_α denote the Dehn twist about α . Let r_n be the Strebel ray through $r_0(0)$ corresponding to the Strebel differential whose set of core curves is $\{T_\alpha^n(\beta_i)\}$ and whose cylinders have equal moduli. This is possible by a theorem of Strebel ([St], Theorem 21.7). Note that $r_n(\infty) = r_0(\infty)$ for each n, since the collection $\{T_\alpha^n(\beta_i)\}$ is combinatorially equivalent to $\{\beta_i\}$. Since the rays are modularly equivalent they are asymptotic (Corollary 3.10 above), so we can choose times $t_n, t'_n \to \infty$ such that $d_{\mathcal{M}(S)}(r_n(t_n), r_0(t'_n))$ is uniformly bounded.

On the other hand the rays r_n converge uniformly on compact sets in time to a ray r_{∞} , where r_{∞} corresponds to the unique one cylinder Strebel differential with core curve α . Taking $r'_n = r_0$ so that $r'_{\infty} = r_0$ for all n, we have $d(r_{\infty}, r'_{\infty}) = \infty$ by Lemma 2.3.

5.2 The set of asymptote classes of all EDM rays

In this subsection we give a parametrization of the set of asymptote classes of all (not necessarily isolated) EDM rays. As we will see, this space is naturally a closed simplex bundle B over $\overline{\mathcal{M}(S)}^{\mathrm{DM}}$. Let S be a surface of genus g with n punctures. The fiber over a point $\hat{X} \in \mathcal{M}_{g',n'}, (g',n') \neq (g,n)$ consists of projective classes (b_1,\ldots,b_p) of vectors. Let Σ be the collection of all asymptotic classes of EDM rays on $\mathcal{M}_{g,n}$. We define a map

$$\Phi: \Sigma \to \mathcal{B}$$
.

Let [r] be an equivalence class of rays. Let r any representative with cylinders C_1, \ldots, C_p with moduli $\operatorname{mod}(C_1), \ldots, \operatorname{mod}(C_p)$). By Corollary 3.10 the projective class of the vector of moduli is independent of the choice of representative and the endpoint $r(\infty)$ is independent of the representative. Define $\Phi([r])$ to be the point whose base is $r(\infty)$ and whose fiber is the projective vector $(\operatorname{mod}(C_1), \ldots, \operatorname{mod}(C_p))$

Theorem 5.1. The map Φ is a homeomorphism onto the open simplex subbundle \mathcal{B}_0 .

Proof. The map Φ is clearly injective. To show surjectivity let $\hat{X} \in \mathcal{M}_{g',n'}$ any point; $v = (M_1, \dots M_j)$ a projective vector. Pick a representative vector v and let (\hat{X}, \hat{q}) be the (unique) quadratic differential on \hat{X} such that

- (\hat{X}, \hat{q}) has double poles at the punctures,
- the vertical trajectories are closed loops isotopic to the punctures
- the lengths of the vertical trajectories are $1/M_i$ for each paired puncture.

This is possible by Theorem 23.5 of [St]. Remove a punctured disc around each paired puncture so that the remaining cylinder has height 1/2. Glue together along the circles. The corresponding cylinders C_i have height 1. The moduli of the cylinders are therefore M_i . We may choose the representative v so that the area of the resulting (X, q) is 1. This gives a corresponding geodesic ray r(t). We have that $\hat{X} = r(\infty)$. so that $\Phi([r]) = (\hat{X}, M_1, \ldots, M_j)$

The quadratic differential (\hat{X}, \hat{q}) depends continuously on \hat{X} and the vector v which implies that the ray [r] depends continuously on these parameters so that the map Φ^{-1} is continuous. The map Φ is continuous because the endpoints and moduli depend continuously on the quadratic differentials defining the ray. \diamond

5.3 Tits geometry of the space of EDM rays

In this section we compute some invariants for pairs of EDM rays. These invariants are fundamental in the study of nonpositively curved manifolds (see, e.g., [Eb], Chapter 3).

Definition 5.2. Let r(t), r'(t) a pair of EDM rays in a metric space (X, d). We define the pre-Tits distance $\ell(r, r')$ between r and r' to be

$$\ell(r, r') := \lim_{t \to \infty} \frac{d(r(t), r'(t))}{t}$$

if the limit exists.

For simply-connected, nonpositively curved manifolds X, the *Tits distance* on the visual boundary ∂X is equal to the path metric induced by ℓ ([Eb], Prop. 3.4.2). The quantity ℓ is related to the angle metric $\angle(r, r')$ on ∂X via

$$\ell(r,r') = 2\sin(\frac{1}{2}\angle(r,r'))$$

(see [Eb], Prop. 3.2.2).

Our goal now is to compute ℓ for pairs of EDM rays in $\mathcal{M}(S)$.

Theorem 5.3. Let r, r' be EDM rays defined by Strebel differentials (X, q) and (X', q') with core curves $\{\gamma_i\}$ and $\{\gamma_j'\}$. The Tits angle between r and r' is 0 if there is an element ϕ of the mapping class group sending $\{\gamma_i\}_{i=1}^p$ to $\{\gamma_j'\}_{i=i}^{p'}$. The angle is 1 if the above does not hold, but there is an element ϕ of the mapping class group such that $i(\phi(\gamma_i), \gamma_j') = 0$ for all γ_i, γ_j' . The angle is 2 otherwise.

This discretization of Tits angles lies in contrast to what happens for higher rank locally symmetric spaces $\Gamma \backslash G/K$, where one has a continuous values of the Tits angles coming from almost isometrically embedded Weyl chambers.

Proof. The first case is if the collection of curves $\{\gamma_i\}$ is combinatorially equivalent to the collection of curves $\{\gamma'_j\}$. That is, there is an element ϕ of the mapping class group sending one collection to the other. Then the corresponding geodesics stay bounded distance apart by [Ma]. Thus the Tits angle is 0.

Thus assume the collections are not combinatorially equivalent. Assume further that any collection of curves combinatorially equivalent to $\{\gamma_i\}$ must intersect some γ'_j . By reindexing we can assume

$$i(\gamma_1, \gamma_1') > 0.$$

Now by Lemma 2.3

$$e^{2t} \operatorname{Ext}_{r(t)}(\gamma_1) \to c_1,$$

for some $c_1 > 0$. Since γ_1 crosses C'_1 ,

$$\operatorname{Ext}_{r'(t)}(\gamma_1) \ge c_2 e^{2t},$$

for some $c_2 > 0$. By Theorem 2.2

$$d_{\mathcal{M}(S)}(r(t), r'(t)) \ge 1/2 \log(c_1 c_2 e^{4t})$$

and so

$$\liminf_{t \to \infty} \frac{d_{\mathcal{M}(S)}(r(t), r'(t))}{t} \ge 2.$$

On the other hand by the triangle inequality

$$\limsup_{t \to \infty} \frac{d_{\mathcal{M}(S)}(r(t), r'(t))}{t} \le 2,$$

and we are done in this case.

The remaining case is that there is some ϕ so that $i(\phi(\gamma_i), \gamma'_j) = 0$ for all i, j. There are several possibilities with similar analyses. Assume for example that after reindexing and applying any element of Mod(S) that $\gamma_1 \neq \gamma'_j$ for all j. Now since

$$i(\gamma_1, \gamma_i') = 0$$

for all j', by Lemma 2.3 we have $\operatorname{Ext}_{r'(t)}(\gamma_1)$ bounded below, and so by Theorem 2.2

$$\liminf_{t \to \infty} \frac{d_{\mathcal{M}(S)}(r(t), r'(t))}{t} \ge 1.$$

We need to show the opposite inequality. That is, we need to show

$$\frac{1}{c(t)e^{2t}} \le \sup_{\beta} \frac{Ext_{r(t)}(\beta)}{Ext_{r'(t)}(\beta)} \le c(t)e^{2t},\tag{8}$$

where

$$\frac{\log c(t)}{t} \to 0.$$

We will use results of Minsky [Mi1] to compare extremal lengths of any β along r(t) and r'(t). We will say that two functions f, g are comparable, denoted $f \approx g$, if f and g differ by fixed multiplicative constants (which in our case will depend only on the genus of S).

Fix some $\epsilon > 0$, smaller than the Margulis constant for S. For sufficiently large t_0 , and for each cylinder C_i along r(t), find a pair of curves γ_i^1, γ_i^2 with the following properties:

- 1. γ_i^1, γ_i^2 are isotopic to γ_i .
- 2. Each has fixed hyperbolic length ϵ .

3. γ_i^1 and γ_i^2 bound a cylinder $\hat{C}_i \subset C_i$ such that $\frac{\text{mod}(\hat{C}_i)}{\text{mod}(C_i)} \to 1$ as $t \to \infty$.

Note that

$$\bmod(C_i) = c_i e^{2t}$$

for some fixed c_i . Let $M_i(t) = \text{mod}(\hat{C}_i)$. The curves γ_i^j define the thick-thin decomposition of r(t). The components Ω_j of the complement of the cylinders \hat{C}_i are thick. According to [Mi1], for any β we have

$$\operatorname{Ext}_{r(t)}(\beta) = \max_{i,j} (\operatorname{Ext}_{\hat{C}_i}(\beta), \operatorname{Ext}_{\Omega_j}(\beta)), \tag{9}$$

which is the maximum of the contribution to the extremal length of β from its intersections with the \hat{C}_i and the Ω_i . These quantities are given below.

For the first, the hyperbolic geodesic representative of β crosses each \hat{C}_i a total of n_i times, twisting t_i times. The contribution to extremal length $\operatorname{Ext}_{\hat{C}_i}(\beta)$ from its intersection with \hat{C}_i is given by

$$\operatorname{Ext}_{\hat{C}_{i}}(\beta) = n_{i}^{2}(M_{i}(t) + t_{i}^{2}/M_{i}(t)). \tag{10}$$

By [Mi1] the contribution to extremal length $\operatorname{Ext}_{\Omega_j}(\beta)$ of β from Ω_j is comparable to $\ell^2(\beta \cap \Omega_j)$, where $\ell(\cdot)$ is length in the hyperbolic metric. This quantity can be computed as follows. Let $\Gamma_j = \Gamma \cap \Omega_j$, the component of the critical graph contained in Ω_j . Choose generators $\omega_1, \ldots, \omega_n$ for $\pi_1(\Gamma_j)$, where n = n(j). Since Ω_j is thick, we have

$$\ell^2(\beta \cap \Omega_j) \simeq (\max_i i(\beta, \omega_i))^2.$$
 (11)

and so

$$\operatorname{Ext}_{\Omega_j}(\beta) \simeq (\max_i i(\beta, \omega_i))^2 \tag{12}$$

Similar estimates hold for the extremal length of β on r'(t). Now assume β crosses C_1 . By assumption, the core curve γ_i of C_1 lies in a thick component Ω'_j of r'(t). By (12), the contribution to the extremal length of β in the thick part of Ω'_j from the n_i crossings of α_i with t_i twists, is comparable to $n_i^2 t_i^2$. The contribution to extremal length of intersections with curves whose homotopy classes lie in both critical graphs are comparable by (12). Comparing the estimate $n_i^2 t_i^2$ to (10) we see that for some c > 0,

$$\frac{e^{-2t}}{c} \le \frac{\operatorname{Ext}_{r(t)}(\beta)}{\operatorname{Ext}_{r'(t)}(\beta)} \le ce^{2t}.$$

The same estimates hold if β crosses a collection of \hat{C}'_i while the γ'_i lie in thick components Ω_i . Thus we see that (8) holds. \diamond

5.4 Refining Minsky's Product Theorem.

Let $C = \{\gamma_1, \ldots, \gamma_p\}$ be a collection of distinct, disjoint, nontrivial homotopy classes of simple closed curves. Let

$$\Omega_{\mathcal{C}}(\epsilon) := \{ X \in \text{Teich}(S) : \ell_X(\gamma_i) < \epsilon \text{ for each } i = 1, \dots, p \}.$$

Extend \mathcal{C} to a maximal collection $\{\gamma_1, \ldots, \gamma_{\zeta(S)}\}$ of homotopy classes of simple closed curves. Let $\{\ell_i, \theta_i\}$ denote the corresponding Fenchel-Nielsen coordinates on $\Omega_{\mathcal{C}}(\epsilon)$. Recall that Fenchel-Nielsen coordinates give global coordinates on Teich(S); henceforth we will identify points in Teich(S) with their corresponding coordinates.

Consider the Teichmüller space Teich($S \setminus C$), which is the space of complete, finite area hyperbolic metrics on $S \setminus C$. Note that the coordinates $\{(\ell_i, \theta_i) : i > p\}$ give Fenchel-Nielsen coordinates on Teich($S \setminus C$).

Let

$$\Psi = (\Psi_1, \Psi_2) : \Omega_{\mathcal{C}}(\epsilon) \to \operatorname{Teich}(S \setminus \mathcal{C}) \times \prod_{i=1}^p \mathbf{H}^2$$

be defined by

$$\Psi((\ell_1, \dots, \ell_{\zeta(S)}, \theta_1, \dots, \theta_{\zeta(S)})) := (\ell_{p+1}, \dots, \ell_{\zeta(S)}, \theta_{p+1}, \dots, \theta_{\zeta(S)}) \times \prod_{i=1}^{p} (\theta_i, 1/\ell_i).$$

Here we are taking coordinates in the upper half-space model of \mathbf{H}^2 and we are endowing the product space in the target with the sup metric, which we denote by d. Further, if $S \setminus \mathcal{C}$ is disconnected, then $\mathrm{Teich}(S \setminus \mathcal{C})$ is itself a product of the Teichmuller spaces of the components of $S \setminus \mathcal{C}$; we endow this product space itself with the sup metric. We remark that Ψ is a homeomorphism onto its image, and its image is $\mathrm{Teich}(S \setminus \mathcal{C}) \times \prod_{i=1}^p \{(x_i, y_i) \in \mathbf{H}^2 : y_i > 1/\epsilon\}$ for some fixed $\epsilon > 0$.

Theorem 5.4. Let the notation be as above. Suppose X_n, Y_n are sequences in Teich(S) such that

1.
$$\ell_{X_n}(\gamma_i) \to 0$$
, $\ell_{Y_n}(\gamma_i) \to 0$, for $i = 1, \ldots, p$.

2. $\Psi_1(X_n), \Psi_1(Y_n)$ lie in bounded set in $Teich(S \setminus C)$.

Then

$$|d(\Psi(X_n), \Psi(Y_n)) - d_{\mathrm{Teich}(S)}(X_n, Y_n)| \to 0.$$

This theorem can be viewed as a refinement of Minsky's Product Theorem [Mi1]. He proved that there exists D such that for all $X, Y \in \Omega_{\mathcal{C}}(\epsilon)$,

$$|d(\Psi(X), \Psi(Y)) - d_{\mathrm{Teich}(S)}(X, Y)| \le D.$$

In Theorem 5.4 we do not know if the conclusion is true without assumption (2).

Proof. Passing to subsequences we can assume $\Psi_1(X_n) \to \hat{X}$ and $\Psi_1(Y_n) \to \hat{Y}$. We first prove that

$$\limsup_{n\to\infty} d_{\mathrm{Teich}(S)}(X_n, Y_n) \le \liminf_{n\to\infty} d(\Psi(X_n), \Psi(Y_n)).$$

The proof is similar to that of Theorem 3.9. Let z_i^1, z_i^2 coordinates about the paired punctures on \hat{X} and let ζ_i^1, ζ_i^2 coordinates in the neighborhood of the corresponding paired punctures on \hat{Y} . This allows us to define (s,t) coordinates about \hat{X} and (s',t') coordinates about \hat{Y} (as in §3.4). Since the hyperbolic length of a homotopy class β of curves is a continuous function of the coordinates (s,t), such a neighborhood contains all surfaces with Fenchel-Nielsen coordinates close to those of \hat{X} . Thus we have that X_n is a surface in the (s,t) coordinate neighborhood of \hat{Y} for large n, The same is true for the surfaces Y_n in a neighborhood of \hat{Y} .

Let $K_0 = e^{d(\hat{X},\hat{Y})}$. Given $\epsilon > 0$, let $F_1 : \hat{Y} \to \hat{X}$ be a $(K_0 + \epsilon)$ -quasiconformal map given by Lemma 3.12 that is conformal in a neighborhood of the punctures. This means that we can take ζ_i^1, ζ_i^2 as conformal coordinates in neighborhoods of the punctures on \hat{X} , and that the map F_1 is the identity in these coordinates inside some disc of radius κ .

We can realize X_n by removing punctured discs $0 < |z_i^j| < \delta_n(i)^{1/2}$ and gluing along boundary circles. This gives annuli of the form

$$B = \{z : \delta_n(i) \le |z_i| \le \kappa\}$$

and similarly Y_n by gluing along circles to form annuli of the form

$$B' = \{ \zeta : \delta'_n(i) \le |\zeta_i| \le \kappa \}.$$

Now let

$$K = d(\Psi_2(X), \Psi_2(Y)).$$

Now exactly as in the proof of Theorem 3.9 we build a $(K + O(\epsilon))$ -quasiconformal map F_2 of the glued annulus B' to the glued annulus B. To do that we again apply Lemma 3.11. We then can glue F_1 to F_2 to give a $\sup(K_0 + \epsilon, K + O(\epsilon))$ -quasiconformal map $F: Y_n \to X_n$.

We now give the inequality in the other direction. We wish to show that for j=1,2 that

$$d(\Psi_j(X), \Psi_j(Y)) \le \liminf_{n \to \infty} d_{\mathrm{Teich}(S)}(X_n, Y_n).$$

For any sequence of quasiconformal maps $f_n: X_n \to Y_n$, there is a subsequence which converges uniformly on compact sets to a limiting $f: \hat{X}_0 \to \hat{Y}_0$. This proves the inequality for j = 1.

For the proof for j=2, suppose the Fenchel-Nielsen twist number of γ_i on Y_n with respect to X_n is θ_n . By Maskit [Mas], for the curve γ_i being pinched,

$$\frac{\operatorname{Ext}_{X_n}(\gamma_i)}{\ell_{X_n}(\gamma_i)} \to 1.$$

This means that we can replace hyperbolic length with extremal length to compute distances in \mathbf{H}^2 . The same argument as in Lemma 2.3 gives

$$\lim_{n\to\infty} (-\log \delta_n(i)) \operatorname{Ext}_{X_n}(\gamma_i) = 1,$$

and similarly for $\delta'_n(i)$ and Y_n . The coordinates for X_n and Y_n in \mathbf{H}^2 can then be taken to be $(0, -\log \delta_n(i))$ and $(\theta_n(i), -\log \delta'_n(i))$.

We can consider the corresponding tori T_n spanned by the vectors $v_1 = (1,0)$ and $v_2 = (0, -\log \delta_n)$ and S_n spanned by $w_1 = (1,0)$ and $w_2 = (\theta_n, -\log \delta'_n)$. The distance between the two points in \mathbf{H}^2 equals $d_{\text{Teich}(T^2)}(T_n, S_n)$ and this in turn is given by $\frac{1}{2} \log K$ where K is the dilatation of the affine map between these tori. Given $\epsilon > 0$ there is a curve β such that

$$|rac{1}{2}\lograc{\mathrm{Ext}_{T_n}(eta)}{\mathrm{Ext}_{S_n}(eta)} - rac{1}{2}\log K| < \epsilon.$$

However if we write $\beta = n_1v_1 + n_2v_2$, there is a corresponding simple closed curve β on the surface that has n_1 intersections with γ_i and twists n_2 times around γ_i without crossing any other short curve. From Equation (9) above, we get

$$\frac{\operatorname{Ext}_{X_n}(\beta)}{\operatorname{Ext}_{T_n}(\beta)} \to 1$$

with the same limit for the ratio of Y_n and S_n . Putting these facts together we get the result. \diamond

One appealing aspect of the proof of Theorem 5.4 is that one can see why the metric on $\Omega_{\mathcal{C}}(S)$ is a sup metric: it follows from the fact that the dilatation of a quasiconformal map is a supremum.

5.5 Appendix

A metric space X is said to have the *local unique extension property* if for every $x \in X$ there is a neighborhood U of x with the property that any two points in U can be connected by a unique geodesic, and further, that such geodesic has a unique extension in U.

The goal of this appendix is to prove the following.

Theorem 5.5 (Uniqueness of product decomposition). Suppose $Z = Y_1 \times Y_2$, where Z is endowed with the sup metric, and where Y_1, Y_2 are connected metric spaces, each of which satisfies the unique local extension property. Then given any other way of writing $Z = X_1 \times \cdots \times X_m$ with the sup metric, it must be that m = 2 and, after perhaps switching factors, $X_i = Y_i$ for i = 1, 2.

Before we begin the proof of Theorem 5.5 we will need some definitions and lemmas. Suppose $X_1 \times \ldots \times X_n$ is a product of metric spaces, given the sup metric. A pair of points $\vec{p} = (p_1, p_2)$ and $\vec{q} = (q_1, q_2)$ in $X_1 \times \ldots \times X_n$ is called a diagonal pair if $d_{X_i}(p_i, q_i) = d_{X_j}(p_j, q_j)$ for $1 \le i, j \le n$. If one of the points is understood, we call the other a diagonal point.

The following lemma follows directly from the definition of the sup metric on $X_1 \times \ldots \times X_n$.

Lemma 5.6 (Characterizing diagonal pairs). Let a diagonal pair \vec{p} , \vec{q} be given as above. Then any geodesic between \vec{p} and \vec{q} is of the form $(r_1(t), \ldots, r_n(t))$, where the $r_i(t)$ are (globally) geodesic segments with the same parametrizations.

Given a basepoint $\vec{x_0} \in X_1 \times ... \times X_n$, we choose $\epsilon > 0$ so that the ϵ -neighborhood of $\vec{x_0}$ satisfies the local unique extension property in each factor. For each $0 \le t < \epsilon$ any choice $r_j(t) \subset X_j$ of geodesic with $\vec{x_0} = (r_1(0), ..., r_n(0))$ and any choice of vector $\vec{a} = (a_1, ..., a_n)$ where each $a_i \pm 1$ we define a diagonal based at $\vec{x_0}$ to be $r^{\vec{a}}(t) = (r_1(a_1t), ..., r_n(a_nt))$.

Lemma 5.7. Suppose Z can be written as $Y_1 \times Y_2$ with the sup metric and as $X_1 \times \ldots \times X_n$ with the sup metric. Then n=2 and the diagonals $(r_1(t),r_2(t))$ and $(r_1(-t),r_2(t)) \subset X_1 \times X_2$ correspond to diagonals $(s_1(t),s_2(t))$ and $(s_1(-t),s_2(t))$ in $Y_1 \times Y_2$.

Proof. Diagonals pairs are characterized as those pairs of points in Z that are connected by a unique geodesic. We thus have by Lemma 5.6 that for each \vec{a} , the diagonal $r^{\vec{a}}(t)$ coincides with a diagonal $(s_1^{\vec{a}}(t), s_2^{\vec{a}}(t)) \subset Y_1 \times Y_2$.

Now let $\vec{r}(t) = (r_1(t), \dots, r_n(t))$ a diagonal with corresponding diagonal $(s_1(t), s_2(t))$. Let $\vec{r'}(t) = (r_1(-t), r_2(t), \dots, r_n(t))$ another diagonal with corresponding $(s'_1(t), s'_2(t))$. Since $d(\vec{r}(t), \vec{r'}(t)) = 2t$, we must have either $d^1(s_1(t), s'_1(t)) = 2t$ or $d^2(s_2(t), s'_2(t)) = 2t$ where d^i is the metric on Y_i . Suppose the former. By the unique continuation property, since each point has distance t from $s_1(0) = s'_1(0)$, we have $s'_1(t) = s_1(-t)$. Since $d(\vec{r}(t), \vec{r'}(-t)) = 2t$ as well, we must have $s'_2(t) = s_2(t)$. Now if n > 2 we may take another diagonal in $X_1 \times \ldots \times X_n$ and it would also correspond to $(s_1(-t), s_2(t))$. But this is a contradiction since the diagonals are distinct. Thus n = 2 and we are done. \diamond

Proof. [of Theorem 5.5] Lemma 5.6 says that after a reindexing, products are preserved in each system. Now we notice that in the above proof there was a reindexing for each

system $\vec{r}(t)$. However within each neighborhood U it follows that the reindexing must be independent of the system of geodesics in that neighborhood. Now since the spaces Y_1, X_1 are assumed to be connected, it follows from the usual open/closed argument that the products are the same globally. \diamond

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