

Review for Midterm-I

Chapter 5. Statistical Inference

§ 5.1 Sampling and Statistics

- **Random sample:** The random variables X_1, \dots, X_n constitute a random sample from a random variable X if they are independent and have identical distribution as X , which is denoted by

$$X_1, \dots, X_n \text{ are iid } \sim F(x) \text{ or } f(x),$$

where $F(x)$ and $f(x)$ are the cdf and pdf of X respectively.

- **Statistic:** Function of the sample $\{X_1, \dots, X_n\}$: $T = T(X_1, \dots, X_n)$
- **Point estimator:** The statistic T is called a point estimator of the unknown parameter θ if the value of T can be used to estimate θ .
- **Unbiasedness:** T is an unbiased estimator of θ if $E(T) = \theta$.
- **Consistency:** T is a consistent estimator of θ if T converges to θ in probability, i.e. $T \xrightarrow{P} \theta$.
- **Confidence interval:** An interval based on the statistic T is called a $100(1 - \alpha)\%$ confidence interval for θ if the probability of the event that the interval covers θ is $(1 - \alpha)$.
- For practice: Example 5.1.1, Exercise 5.1.2

§ 5.2.1 Quantiles

- **Quantile:** For $0 < p < 1$, the p th quantile of a random variable X is $\xi_p = F^{-1}(p)$, where $F(x)$ is the cdf of X . Note: If $F(x)$ is not monotone, we may define $F^{-1}(p) = \min\{x : F(x) \geq p\}$.
- **Order statistics:** Let X_1, \dots, X_n denote a random sample. Rewrite the sample in ascending order and obtain $X_{(1)} \leq X_{(2)} \leq \dots \leq X_{(n)}$, which are called the order statistics of the sample.
- **Percentile:** Let X_1, \dots, X_n be a random sample and let $X_{(1)} \leq X_{(2)} \leq \dots \leq X_{(n)}$ be the corresponding order statistics. For $0 < p < 1$, let $k = [p(n + 1)]$, where $[x]$ represents the greatest integer m such that $m \leq x$. Then $X_{(k)}$ is called the p th sample quantile or the $100p$ th percentile of the sample.
- **Five number summary:** The minimum ($Min = X_{(1)}$), the first quartile (Q_1), the median (Q_2), the third quartile (Q_3), and the maximum ($Max = X_{(n)}$).

- **Boxplot:** Box part (Q_1, Q_2 , and Q_3), whisker part ($LF = Q_1 - 1.5 * IQR, UF = Q_3 + 1.5 * IQR$), where the interquartile range $IQR = Q_3 - Q_1$. Potential outliers (points that lie outside of (LF, UF)).
- For practice: Example 5.2.4, Example 5.2.5

§ 5.5 Hypothesis Testing

- Null hypothesis H_0 versus alternative hypothesis H_1 . For example:
 $H_0 : \theta = \theta_0$ versus $H_1 : \theta > \theta_0$ (one-sided test);
 $H_0 : \theta = \theta_0$ versus $H_1 : \theta \neq \theta_0$ (two-sided test)
- **Type I error** (or significance level, or size of test):
 $\alpha = P(\text{reject } H_0 | \theta = \theta_0)$.
- **Type II error:** $\beta(\theta_1) = P(\text{do not reject } H_0 | \theta = \theta_1), \theta_1 \neq \theta_0$
- **Power function** (or power of test at $\theta = \theta_1$):
 $1 - \beta(\theta_1) = P(\text{reject } H_0 | \theta = \theta_1)$
- For practice: Example 5.5.2, Example 5.5.4

§ 5.7 Chi-Square Test

- Chi-Square Test for Multinomial Distribution: $H_0 : p_i = p_{i0}, i = 1, \dots, k$. Given that H_0 is true, then

$$Q_{k-1} = \sum_{i=1}^k \frac{(X_i - n \cdot p_{i0})^2}{n \cdot p_{i0}} \sim \chi^2(k-1).$$

Critical region is $\{Q_{k-1} > \chi^2_{\alpha}(k-1)\}$ if the significance level is α .

- Chi-Square Test for independence of the two variables in contingency table: $H_0 : p_{ij} = p_{i \cdot} \cdot p_{\cdot j}, \forall i = 1, \dots, a, j = 1, \dots, b$. Given that H_0 is true, then

$$Q = \sum_{i=1}^a \sum_{j=1}^b \frac{(X_{ij} - n \cdot \hat{p}_{i \cdot} \cdot \hat{p}_{\cdot j})^2}{n \cdot \hat{p}_{i \cdot} \cdot \hat{p}_{\cdot j}} \sim \chi^2((a-1)(b-1))$$

where $\hat{p}_{i \cdot} = \frac{1}{n} \sum_{j=1}^b X_{ij}, \hat{p}_{\cdot j} = \frac{1}{n} \sum_{i=1}^a X_{ij}$.

Critical region is $\{Q_{k-1} > \chi^2_{\alpha}((a-1)(b-1))\}$

- For practice: Example 5.7.1

§ 5.8 The Method of Monte Carlo (not required)

Chapter 6. Maximum Likelihood Methods

§ 6.1 Maximum Likelihood Estimation

- **Likelihood function:** $L(\theta) = \prod_{i=1}^n f(x_i; \theta)$, if X_1, \dots, X_n are iid $\sim f(x; \theta)$.
- **Log likelihood function:** $l(\theta) = \log L(\theta) = \sum_{i=1}^n \log f(x_i; \theta)$
- **M.L.E.:** The value of θ which maximizes $L(\theta)$ or $l(\theta)$ is called the maximum likelihood estimator of θ , denoted by $\hat{\theta}$ or $\hat{\theta}_{MLE}$.
- **Theorem 6.1.1:** Let θ_0 be the true value of θ . Under regularity conditions,

$$\lim_{n \rightarrow \infty} P_{\theta_0}[L(\theta_0; \mathbf{X}) > L(\theta; \mathbf{X})] = 1, \text{ for all } \theta \neq \theta_0$$

- **Theorem 6.1.2:** Suppose $\hat{\theta}$ is the mle of θ , then $g(\hat{\theta})$ is the mle of $g(\theta)$.
- **Theorem 6.1.3:** Under regularity conditions, the likelihood equation $\frac{\partial}{\partial \theta} l(\theta) = 0$ has a solution $\hat{\theta}_n$ such that $\hat{\theta}_n \xrightarrow{P} \theta_0$.
- **Corollary 6.1.1:** Under regularity conditions, if the likelihood equation has a unique solution $\hat{\theta}_n$, then $\hat{\theta}_n$ is a consistent estimator of θ_0 .
- For practice: Example 6.1.1, Example 6.1.2, Example 6.1.5, Example 6.1.6

§ 6.2 Rao-Cramér Lower Bound and Efficiency

- Let X be a random variable with pdf $f(x; \theta)$, $\theta \in \Omega$. Under regularity conditions,

$$E \left[\frac{\partial \log f(X; \theta)}{\partial \theta} \right] = 0, \quad E \left[\left(\frac{\partial \log f(X; \theta)}{\partial \theta} \right)^2 \right] = -E \left[\frac{\partial^2 \log f(X; \theta)}{\partial \theta^2} \right]$$

- **Fisher information of a single random variable X :**

$$I(\theta) = E \left[\left(\frac{\partial \log f(X; \theta)}{\partial \theta} \right)^2 \right] = \text{Var} \left(\frac{\partial \log f(X; \theta)}{\partial \theta} \right) = -E \left[\frac{\partial^2 \log f(X; \theta)}{\partial \theta^2} \right]$$

- **Fisher information of a random sample X_1, \dots, X_n :** $nI(\theta)$
- **Theorem 6.2.1 (Rao-Cramér Lower Bound):** Let X_1, \dots, X_n be iid $\sim f(x; \theta)$. Let $Y = u(X_1, \dots, X_n)$ be a statistic with mean $k(\theta)$. Under regularity conditions,

$$\text{Var}(Y) \geq \frac{[k'(\theta)]^2}{nI(\theta)}$$

- **Corollary 6.2.1:** Under the assumptions of Theorem 6.2.1, if Y is an unbiased estimator of θ , then $\text{Var}(Y) \geq \frac{1}{nI(\theta)}$.
- **Efficient estimator:** Let Y be an unbiased estimator of θ . Y is called an efficient estimator of θ if $\text{Var}(Y)$ attains the Rao-Cramér lower bound.
- **Efficiency:** Let Y be an unbiased estimator of θ . Then $\frac{1}{nI(\theta)}[\text{Var}(Y)]^{-1}$ is called the efficiency of Y .
- **Theorem 6.2.2:** Assume X_1, \dots, X_n are iid with pdf $f(x; \theta_0)$. Suppose $0 < I(\theta_0) < \infty$ and $\hat{\theta}_n$ is a consistent estimator of θ_0 such that $\frac{\partial}{\partial \theta} l(\hat{\theta}_n) = 0$. Under regularity conditions,

$$\sqrt{n}(\hat{\theta}_n - \theta_0) \xrightarrow{D} N\left(0, \frac{1}{I(\theta_0)}\right)$$

- **Corollary 6.2.2:** Suppose $g(x)$ is differentiable at θ_0 and $g'(\theta_0) \neq 0$. Under the assumptions of Theorem 6.2.2,

$$\sqrt{n}(g(\hat{\theta}_n) - g(\theta_0)) \xrightarrow{D} N\left(0, \frac{[g'(\theta_0)]^2}{I(\theta_0)}\right)$$

- For practice: Example 6.2.1, Example 6.2.2, Example 6.2.3

§ 6.3 Maximum Likelihood Tests

- **Likelihood ratio test statistic:** $\Lambda = L(\theta_0)/L(\hat{\theta})$, where $\hat{\theta}$ is the mle of θ .
- **Likelihood ratio test (two-sided):** Reject H_0 in favor of H_1 if $\Lambda \leq c$.
- **Theorem 6.3.1:** Assume the same regularity conditions as for Theorem 6.2.2. Under the null hypothesis $H_0 : \theta = \theta_0$, $-2 \log \Lambda \xrightarrow{D} \chi^2(1)$.
- For practice: Example 6.3.1, Example 6.3.2

§ 6.4 Multiparameter Case: Estimation

- **Parameters:** Let X_1, \dots, X_n be iid $\sim f(x; \boldsymbol{\theta})$, where $\boldsymbol{\theta} = (\theta_1, \dots, \theta_p)'$.
Likelihood function: $L(\boldsymbol{\theta}) = \prod_{i=1}^n f(x_i; \boldsymbol{\theta})$;
Log likelihood function: $l(\boldsymbol{\theta}) = \log L(\boldsymbol{\theta}) = \sum_{i=1}^n \log f(x_i; \boldsymbol{\theta})$.
MLE: The value of $\boldsymbol{\theta}$ which maximizes $L(\boldsymbol{\theta})$ or $l(\boldsymbol{\theta})$ is called the maximum likelihood estimator (mle) of $\boldsymbol{\theta}$ and denoted by $\hat{\boldsymbol{\theta}}$.
- Under regularity conditions, the gradient is

$$\nabla \log f(x, \boldsymbol{\theta}) = \left(\frac{\partial}{\partial \theta_1} \log f(X; \boldsymbol{\theta}), \dots, \frac{\partial}{\partial \theta_p} \log f(X; \boldsymbol{\theta}) \right)$$

$$E[\nabla \log f(x, \boldsymbol{\theta})] = 0, E\left[\frac{\partial}{\partial \theta_j} \log f(X; \boldsymbol{\theta})\right] = 0, \text{ for } j = 1, \dots, p;$$

$$\text{Cov}\left(\frac{\partial}{\partial \theta_j} \log f(X; \boldsymbol{\theta}), \frac{\partial}{\partial \theta_k} \log f(X; \boldsymbol{\theta})\right) = -E\left[\frac{\partial^2}{\partial \theta_j \partial \theta_k} \log f(X; \boldsymbol{\theta})\right]$$

– **Fisher information matrix:**

$$\mathbf{I}(\boldsymbol{\theta}) = \text{Cov}(\nabla \log f(x, \boldsymbol{\theta})) = (I_{jk})_{p \times p},$$

where

$$I_{jk} = -E\left[\frac{\partial^2}{\partial \theta_j \partial \theta_k} \log f(X; \boldsymbol{\theta})\right]$$

– **Theorem:** Under regularity conditions, if $Y = u(X_1, \dots, X_n)$ is an unbiased estimate of θ_j , then

$$\text{Var}(Y) \geq \frac{1}{n} [\mathbf{I}^{-1}(\boldsymbol{\theta})]_{jj}$$

– **Theorem 6.4.1:** Let X_1, \dots, X_n be iid $\sim f(x; \boldsymbol{\theta})$. Under regularity conditions, any consistent solution sequence $\hat{\boldsymbol{\theta}}_n$ of the likelihood equation $\frac{\partial}{\partial \boldsymbol{\theta}} l(\boldsymbol{\theta}) = \mathbf{0}$

$$\sqrt{n}(\hat{\boldsymbol{\theta}}_n - \boldsymbol{\theta}) \xrightarrow{D} N_p(\mathbf{0}, \mathbf{I}^{-1}(\boldsymbol{\theta}))$$

– **Corollary.** Let \mathbf{g} be a transformation $\mathbf{g}(\boldsymbol{\theta}) = (g_1(\boldsymbol{\theta}), \dots, g_k(\boldsymbol{\theta}))^T$, such that $1 \leq k \leq p$. and the $k \times p$ matrix of partial derivatives:

$$\mathbf{B} = \left[\frac{\partial g_i}{\partial \theta_j} \right], i = 1, \dots, k; j = 1, \dots, p$$

has continuous elements and does not vanish in a neighborhood of $\boldsymbol{\theta}$. Let $\hat{\boldsymbol{\eta}} = \mathbf{g}(\hat{\boldsymbol{\theta}})$, then $\hat{\boldsymbol{\eta}}$ is the mle of $\boldsymbol{\eta} = \mathbf{g}(\boldsymbol{\theta})$, and

$$\sqrt{n}(\hat{\boldsymbol{\eta}} - \boldsymbol{\eta}) \xrightarrow{D} N(\mathbf{0}, \mathbf{B} \mathbf{I}^{-1}(\boldsymbol{\theta}) \mathbf{B}^T)$$

and the information matrix for $\boldsymbol{\eta}$ is $\mathbf{I}(\boldsymbol{\eta}) = (\mathbf{B} \mathbf{I}^{-1}(\boldsymbol{\theta}) \mathbf{B}^T)^{-1}$

– For practice: Example 6.4.1, Example 6.4.3, Example 6.4.4, Example 6.4.6